CORE DISCUSSION PAPER 2006/117

NETWORK FORMULATIONS OF MIXED-INTEGER PROGRAMS

Michele Conforti¹, Marco Di Summa¹, Fritz Eisenbrand² and Laurence A. Wolsey³

December 2006

Abstract

We consider mixed-integer sets of the type $MIX^{TU} = \{x : Ax \ge b; x_i \text{ integer}, i \in I\}$, where A is a totally unimodular matrix, b is an arbitrary vector and I is a nonempty subset of the column indices of A. We show that the problem of checking nonemptiness of a set MIX^{TU} is NP-complete when A contains at most two nonzeros per column.

This is in contrast to the case when A is TU and contains at most two nonzeros per row. Denoting the set by MIX^{2TU} , we provide an extended formulation for the convex hull of MIX^{2TU} whose constraint matrix is the dual of a network matrix, and with integer right hand side vector. The size of this formulation depends on the number |F| of distinct fractional parts taken by the continuous variables in the extreme points of conv(MIX^{2TU}). When this number is polynomial in the dimension of the matrix A, the formulation is of polynomial size and the optimization problem over MIX^{2TU} lies in \mathcal{P} . We show that there are instances for which |F| is of exponential size, and we also give conditions under which |F| is of polynomial size. Finally we show that these results for the set MIX^{2TU} provide a unified framework leading to polynomial-size extended formulations for several generalizations of mixing sets and lot-sizing sets studied in the last few years.

Keywords: mixed-integer set, totally unimodular matrix, extended formulation, convex hull, dual of network matrix.

¹Dipartimento di Matematica Pura ed Applicata, Università degli Studi di Padova. Via Trieste 63, 35121 Padova, Italy (conforti@math.unipd.it, mdsumma@math.unipd.it).

²Department of Mathematics, Paderborn University. Warburger Str. 100, D-33098, Paderborn, Germany (eisen@math.uni-paderborn.de).

³Center of Operations Research and Econometrics (CORE) and INMA, Université catholique de Louvain. 34, Voie du Roman Pays, 1348 Louvain-la-Neuve, Belgium (wolsey@core.ucl.ac.be).

This work was partly carried out within the framework of ADONET, a European network in Algorithmic Discrete Optimization, contract no. MRTN-CT-2003-504438. This text presents research results of the Belgian Program on Interuniversity Poles of Attraction initiated by the Belgian State, Prime Minister's Office, Science Policy Programming. The scientific responsability is assumed by the authors.

1 Introduction

We study mixed-integer sets of the type

$$MIX^{TU} = \{x : Ax \ge b; x_i \text{ integer}, i \in I\},\$$

where A is a totally unimodular (TU, for short) matrix, b is a vector that typically contains fractional components and I is a nonempty subset of the column indices of A. (Definitions and properties of TU matrices can be found in [12].)

We show that the problem of checking nonemptiness of a set MIX^{TU} is NP-complete, even if A is a TU matrix with at most two nonzero entries per column and b is a half-integral vector, i.e. 2b is integral. Let $conv(MIX^{TU})$ be the convex hull of the set MIX^{TU} . This, together with the equivalence between separation and optimization, shows that finding an explicit inequality description of the polyhedron $conv(MIX^{TU})$ will most likely be an elusive task.

Let MIX^{2TU} be the mixed-integer set MIX^{TU} with the additional restriction that A is a TU matrix with at most two nonzero entries per row. We provide an extended formulation for the polyhedron conv (MIX^{2TU}) .

We use the following terminology. A *formulation* of a polyhedron P (in its original space) is a description of P as the intersection of a finite number of half-spaces. So it consists of a finite set of inequalities such that $P = \{x : Cx \ge d\}$. A formulation of P is *extended* whenever it gives a polyhedral description of the type $Q = \{(x, \mu) : Ax + B\mu \ge d\}$ in a space that uses variables (x, μ) and includes the original x-space, so that P is the projection of Q onto the x-space.

The extended formulation of the polyhedron $conv(MIX^{2TU})$ takes explicitly into account all possible fractional parts taken by the continuous variables at the vertices of $conv(MIX^{2TU})$. If the number of these fractional parts is small, we show that this extended formulation is compact. This shows that optimizing a linear function over sets MIX^{2TU} that have this property can be carried out efficiently through linear programming.

For a mixed-integer set M, define a formulation (which may be extended) of the polyhedron conv(M) to be *compact* if the size of its system of inequalities is polynomial in the size of the original description of M (which typically is given as the set of mixed-integer vectors that satisfy a given system of linear inequalities).

We construct mixed-integer sets of the type MIX^{2TU} for which the length of the list of all fractional parts taken by the continuous variables at the vertices of $conv(MIX^{2TU})$ is exponential with respect to the size of the description of the set. On the other hand, we also give conditions guaranteeing that the list of fractional parts is of polynomial size.

We then introduce invertible linear transformations that map mixed-integer vectors into mixed-integer vectors and we show that a host of mixed-integer sets that have been investigated in the past decade can be mapped with these transformations into sets of the type MIX^{2TU} with a small number of fractional parts taken by the continuous variables. Therefore our result provides a general setting for the compact extended formulations of all these mixed-integer sets.

2 Network matrices

We recall here some basic facts about the matrices that are the object of this study. The following characterization is due to Heller and Tompkins [9], see e.g. Theorem 2.8 in [12].

Theorem 1 Let A be a $0, \pm 1$ -matrix with at most two nonzero entries per row, where $\{a_j, j \in N\}$ is the set of columns of A. Then A is totally unimodular if and only if the set N can be partitioned into two classes (R, B) such that all entries of the vector $\sum_{j \in R} a_j - \sum_{j \in B} a_j$ are $0, \pm 1$.

A $0, \pm 1$ -matrix A with at most two nonzero entries per row is a *dual network* matrix if A has the following property:

If a_{ij} , a_{ik} are both nonzero, then $a_{ij} = -a_{ik}$.

Dual network matrices are the transpose of *network matrices*, the constraint matrices of circulation problems on a network. Theorem 1 has the following well-known consequence:

Corollary 2 Let A be a $0, \pm 1$ -matrix with at most two nonzero entries per row, where $\{a_j, j \in N\}$ is the set of columns of A. Then A is totally unimodular if and only if N contains a subset R such that the matrix A^R , obtained by multiplying by -1 the columns $a_j, j \in R$, is a dual network matrix.

Proof: Let (R, B) be a partition of the column indices of A satisfying the condition of Theorem 1. Then A^R is a dual network matrix.

3 Complexity

Let $X^N = \{x : Ax \ge b; x_i \text{ integer}, i \in I\}$, where A is a network matrix, I is a nonempty subset of the column indices of A and b is a vector such that 2b is integral. In this section we show the following:

Theorem 3 The problem of deciding the nonemptiness of a set X^N is NP-complete.

Proof: Since A is a TU matrix and b is half-integral, then X^N , if nonempty, contains a vector whose length is polynomial in the length of the encoding of $(A \mid b)$. So the above problem is in NP.

Consider the set

$$Y^N = \{ y : Ay \ge b'; y \text{ integer}; y_i \text{ even}, i \in I \},\$$

where b' = 2b. Remark that X^N is nonempty if and only if X^N contains a vector x such that 2x is integral. Therefore X^N and Y^N are either both empty or both nonempty.

Since A is a network matrix, deciding the nonemptiness of Y^N includes the following problem:

Detecting whether a network (having A as node-arc incidence matrix), with integer requirements on the nodes and integer capacities on the arcs (corresponding to the values of b'), admits an integral circulation with the additional condition that the value of the circulation is even on some subset of arcs (indexed with I), defined to be special. We reduce CNF-SAT to the above problem in a manner similar to that introduced by Even et al. in the proof that the edge-disjoint paths problem is NP-hard, see [6] and [10, p. 432]. Given a CNF-SAT formula over the variables x_1, \ldots, x_n , consisting of clauses Z_1, \ldots, Z_m , we construct a network D = (V, A) having some special arcs as follows:

- The set V of nodes of D consists of a source s, a sink t and a node z_j , $1 \le j \le m$, that represents the corresponding clause. Every variable x_i appearing in true or negated form in clauses $Z_{i_1}, \ldots, Z_{i_{p_i}}$ is represented by a "value node" v_i and nodes $x_{i,i_\ell}^{in}, x_{i,i_\ell}^{out}, \bar{x}_{i,i_\ell}^{in}, \bar{x}_{i,i_\ell}^{out}, 1 \le \ell \le p_i$. Finally there is an additional value node v_{n+1} .
- The arcs of D that are not special (unspecified capacities are unlimited) are:
 - The arcs $sx_{i,i_{\ell}}^{in}$, $s\bar{x}_{i,i_{\ell}}^{in}$, $1 \leq i \leq n, 1 \leq \ell \leq p_i$.
 - The arcs $z_j t$, $1 \le j \le m$, having capacity 1.
 - The arcs $x_{i,i_{\ell}}^{in} x_{i,i_{\ell}}^{out}$ and $\bar{x}_{i,i_{\ell}}^{in} \bar{x}_{i,i_{\ell}}^{out}$, $1 \leq i \leq n, 1 \leq \ell \leq p_i$, having capacity 2.
 - If variable x_i occurs as a positive literal in clause Z_{i_ℓ} , there is an arc $x_{i,i_\ell}^{out} z_{i_\ell}$. If variable x_i occurs as a negative literal in clause Z_{i_ℓ} , there is an arc $\bar{x}_{i,i_\ell}^{out} z_{i_\ell}$.
- The following are the arcs of D that are special and carry a flow of even value:
 - The arcs $v_i x_{i,i_1}^{in}$ and $v_i \bar{x}_{i,i_1}^{in}$, $1 \leq i \leq n$.
 - The arcs $x_{i,i_{p_i}}^{out}v_{i+1}$ and $\bar{x}_{i,i_{p_i}}^{out}v_{i+1}$, $1 \le i \le n$.
 - The arcs $x_{i,i_{\ell}}^{out} x_{i,i_{\ell+1}}^{in}$ and $\bar{x}_{i,i_{\ell}}^{out} \bar{x}_{i,i_{\ell+1}}^{in}$, $1 \le i \le n, 1 \le \ell < p_i$.
- The circulation requirements are:
 - An in-flow of value m in the source s and an out-flow of value m in the sink t.
 - An in-flow of value 2 at v_1 and an out-flow of value 2 at v_{n+1} .

Figure 1 shows the network relative to the CNF-SAT formula $(x_1 \lor \bar{x}_2) \land (x_2 \lor x_3)$.

For $1 \leq i \leq n$, define the upper path P_i^U to be $v_i, x_{i,i_1}^{in}, x_{i,i_1}^{out}, \dots, x_{i,i_{p_i}}^{in}, x_{i,i_{p_i}}^{out}, v_{i+1}$ and the lower path P_i^L to be $v_i, \bar{x}_{i,i_1}^{in}, \bar{x}_{i,i_1}^{out}, \dots, \bar{x}_{i,i_{p_i}}^{in}, \bar{x}_{i,i_{p_i}}^{out}, v_{i+1}$. Observe that the special arcs force any feasible circulation F to satisfy the following

Observe that the special arcs force any feasible circulation F to satisfy the following conditions:

- For every $1 \le i \le n$, the special arcs of one among P_i^U and P_i^L carry a flow of value 2, and the special arcs of the other carry a flow of value 0.
- For every $1 \leq j \leq m$, F carries a flow of value 1 along a path of the type $s, x_{i,j}^{in}, x_{i,j}^{out}, z_j, t$ and the upper path P_i^U is discharged (that is, its special arcs carry a flow of value 0), or a flow of value 1 along a path of the type $s, \bar{x}_{i,j}^{in}, \bar{x}_{i,j}^{out}, z_j, t$ and the lower path P_i^L is discharged.

To any truth assignment T that satisfies the CNF-formula, we assign a flow value of 2 to P_i^L if $x_i = true$ in T and a flow value of 2 to P_i^U if $x_i = false$ in T. For each clause Z_j we choose a literal x_i or \bar{x}_i which is true under T. Say x_i occurs as a positive literal in



Figure 1: The network corresponding to the CNF-SAT formula $(x_1 \vee \bar{x}_2) \wedge (x_2 \vee x_3)$. Thick arcs are special arcs. Numbers on arcs are capacities.

 Z_j and $x_i = true$ in T. Then P_i^U is discharged and a flow of value 1 can be routed along $s, x_{i,j}^{in}, x_{i,j}^{out}, z_j, t$.

It is immediate to see that the converse also holds: to any feasible circulation, a truth assignment that satisfies all clauses can be derived in the above manner. \Box

4 The main result

Let $\mathcal{F} = \{f_1 > f_2 > \cdots > f_k\}$ be a list of fractional parts (that is, $0 \leq f_\ell < 1$ for $1 \leq \ell \leq k$), $K = \{1, \ldots, k\}$ be its set of indices and $N = \{1, \ldots, n\}$. Let $X^{\mathcal{F}}$ be the set of points $x \in \mathbb{R}^n$ such that there exist $\mu^i, \delta^i_\ell, i \in N, \ell \in K$, satisfying the following constraints:

$$x_i = \mu^i + \sum_{\ell=1}^k f_\ell \delta^i_\ell, \quad i \in N$$
(1)

$$\sum_{\ell=1}^{k} \delta_{\ell}^{i} = 1, \ \delta_{\ell}^{i} \ge 0, \quad i \in N, \ell \in K$$

$$\tag{2}$$

$$x_i - x_j \ge l_{ij}, \qquad (i,j) \in N^e \tag{3}$$

$$x_i \ge l_i, \qquad i \in N^l \tag{4}$$

$$x_i \le u_i, \qquad i \in N^u \tag{5}$$

$$\mu^i$$
 integer, δ^i_{ℓ} integer, $i \in N, \ell \in K$, (6)

where $N^e \subseteq N \times N$ and $N^l, N^u \subseteq N$. In other words, $X^{\mathcal{F}}$ is the projection onto the *x*-space of the mixed-integer set (1)–(6). We remark that the above system may also include constraints of the type $x_i - x_j \leq u_{ij}$, as this inequality is equivalent to $x_j - x_i \geq l_{ij}$ for $l_{ij} = -u_{ij}$. In this section we give an extended formulation for the polyhedron $\operatorname{conv}(X^{\mathcal{F}})$.

Consider the following unimodular transformation:

$$\mu_0^i = \mu^i, \ \mu_\ell^i = \mu^i + \sum_{j=1}^\ell \delta_j^i, \ i \in N, \ell \in K.$$
(7)

Define $f_0 = 1$ and $f_{k+1} = 0$. For fixed $i \in N$, an equation in (1) becomes:

$$x_i = \sum_{\ell=0}^k \mu_\ell^i (f_\ell - f_{\ell+1})$$
(8)

and the k + 1 inequalities in (2) become:

$$\mu_k^i - \mu_0^i = 1, \ \mu_\ell^i - \mu_{\ell-1}^i \ge 0, \ \ell \in K.$$
(9)

Given a real number α , we denote with $f(\alpha) = \alpha - \lfloor \alpha \rfloor$ its fractional part.

4.1 Modeling $x_i \ge l_i$ and $x_i \le u_i$

Let ℓ_{l_i} be the highest index $\ell \in \{0, \ldots, k\}$ such that $f_\ell \ge f(l_i)$. Now if $x_i, \delta^i_\ell, \mu^i_\ell$ satisfy (1), (2), (6), (7), then $x_i \ge l_i$ if and only if

$$\mu_{\ell_{l_i}}^i \ge \lfloor l_i \rfloor + 1. \tag{10}$$

Similarly if ℓ_{u_i} is the highest index such that $f_{\ell} > f(u_i)$, then constraint $x_i \leq u_i$ is satisfied if and only if

$$\mu_{\ell_{u_i}}^i \le \lfloor u_i \rfloor \,. \tag{11}$$

4.2 Modeling $x_i - x_j \ge l_{ij}$

Define k_{ij} to be the highest index $\ell \in \{0, \ldots, k\}$ such that $f_{\ell} + f(l_{ij}) \ge 1$. Given an index $t \in K$, define k_t to be the highest index $\ell \in \{0, \ldots, k\}$ such that $f_{\ell} \ge f(f_t + f(l_{ij}))$.

Lemma 4 Assume $x_i, x_j, \delta^i_{\ell}, \delta^j_{\ell}, \mu^i_{\ell}, \mu^j_{\ell}$ satisfy (1), (2), (6), (7). Then $x_i - x_j \ge l_{ij}$ if and only if the following set of inequalities is satisfied:

$$\mu_{k_t}^i - \mu_t^j \ge \lfloor l_{ij} \rfloor + 1, \quad 1 \le t \le k_{ij} \tag{12}$$

$$\mu_{k_t}^i - \mu_t^j \ge \lfloor l_{ij} \rfloor, \quad k_{ij} < t \le k.$$
(13)

Proof: Substituting for x_i and x_j , the inequality $x_i - x_j \ge l_{ij}$ becomes

$$\mu^{i} + \sum_{\ell=1}^{k} f_{\ell} \delta^{i}_{\ell} \ge \mu^{j} + \sum_{\ell=1}^{k} f_{\ell} \delta^{j}_{\ell} + \lfloor l_{ij} \rfloor + f(l_{ij}).$$

First we show that the inequality is valid for $t > k_{ij}$. As $\sum_{\ell > k_t} f_\ell \delta^i_\ell \le f_{k_t+1}$ and $\sum_{\ell=1}^k f_\ell \delta^j_\ell \ge \sum_{\ell \le t} f_\ell \delta^j_\ell \ge f_t \sum_{\ell \le t} \delta^j_\ell$, we obtain the valid inequality

$$\mu^{i} + \sum_{\ell \leq k_{t}} f_{\ell} \delta^{i}_{\ell} \geq \mu^{j} + f_{t} \sum_{\ell \leq t} \delta^{j}_{\ell} + \lfloor l_{ij} \rfloor + f(l_{ij}) - f_{k_{t}+1}.$$

Adding the valid inequality $(1 - f_t) \ge (1 - f_t) \sum_{\ell \le t} \delta_{\ell}^j$ gives

$$\mu^{i} + \sum_{\ell \le k_{t}} f_{\ell} \delta^{i}_{\ell} + 1 - f_{t} \ge \mu^{j} + \sum_{\ell \le t} \delta^{j}_{\ell} + \lfloor l_{ij} \rfloor + f(l_{ij}) - f_{k_{t}+1}.$$

As by definition $f(l_{ij}) + f_t > f_{k_t+1}$ and $\delta^i_{\ell}, \delta^j_{\ell} \ge 0$ for all $\ell \in K$, Chvátal-Gomory rounding gives

$$\mu^{i} + \sum_{\ell \leq k_{t}} \delta^{i}_{\ell} \geq \mu^{j} + \sum_{\ell \leq t} \delta^{j}_{\ell} + \lfloor l_{ij} \rfloor, \text{ or}$$
$$\mu^{i}_{k_{t}} \geq \mu^{j}_{t} + \lfloor l_{ij} \rfloor.$$

The argument when $t \leq k_{ij}$ is the same, except that $f(l_{ij}) - f_{k_t+1} + f_t > 1$.

To establish the converse, we consider the case in which $\delta_t^j = 1$. Then $\mu_t^j = \mu_0^j + 1$, $\mu_{t-1}^j = \mu_0^j$ and

$$x_j = \mu_0^j + \sum_{\ell=1}^k (\mu_\ell^j - \mu_{\ell-1}^j) f_\ell = \mu_0^j + f_t.$$

Inequality $\mu_{k_t}^i \ge \mu_t^j + \lfloor l_{ij} \rfloor$ implies that either $\mu_0^i \ge \mu_0^j + 1 + \lfloor l_{ij} \rfloor$ or that $\mu_0^i = \mu_0^j + \lfloor l_{ij} \rfloor$ and $\sum_{\ell \le k_t} \delta_{\ell}^i = 1$. This implies that $x_i \ge \mu_0^j + \lfloor l_{ij} \rfloor + f_{k_t}$. Now, assuming $t > k_{ij}$,

$$\begin{aligned} x_i - x_j &\geq \mu_0^j + \lfloor l_{ij} \rfloor + f_{k_t} - \mu_0^j - f_t \\ &= \lfloor l_{ij} \rfloor + f_{k_t} - f_t \\ &\geq \lfloor l_{ij} \rfloor + f(l_{ij}), \end{aligned}$$

as $f_{k_t} \ge f(f_t + f(l_{ij}))$ and $f_t + f(l_{ij}) < 1$. Again the other case with $t \le k_{ij}$ is similar. \Box

Let $Q^{\mathcal{F}}$ be the polyhedron on the space of the variables $\{(x_i, \mu_{\ell}^i), i \in N, \ell \in K \cup \{0\}\}$ defined by the inequalities

$$\begin{array}{ll} (8), (9), & i \in N \\ (10), & i \in N^l \\ (11), & i \in N^u \\ (12), (13), & (i,j) \in N^e \end{array}$$

Theorem 5 The polyhedron $\operatorname{conv}(X^{\mathcal{F}})$ is the projection onto the space of the x-variables of the polyhedron $Q^{\mathcal{F}}$.

Proof: Since, for $i \in N$, variable x_i is determined by the corresponding equation (8), we only need to show that the polyhedron defined by inequalities

(9),
$$i \in N$$

(10), $i \in N^{l}$
(11), $i \in N^{u}$
(12), (13), $(i, j) \in N^{e}$

is integral. Let A_{μ} be the constraint matrix of the above system. By construction A_{μ} is a dual network matrix. Since dual network matrices are totally unimodular and the right-hand-sides of the above inequalities are all integer, the statement follows from the theorem of Hoffman and Kruskal.

5 An extended formulation for $conv(MIX^{2TU})$

Let $X = \{x : Ax \ge b; x_i \text{ integer}, i \in I\}$ be a mixed-integer set, where $(A \mid b)$ is a rational matrix and I is a nonempty subset of the column indices of A. A list $\mathcal{F} = \{f_1 > f_2 \cdots > f_k\}$ of fractional parts is *complete* for X if the following property is satisfied:

Every minimal face
$$F$$
 of $conv(X)$ contains a point \bar{x} such that
for each $i \in N$, $f(\bar{x}_i) = f_j$ for some $f_j \in \mathcal{F}$ and for each $i \in I$, $f(\bar{x}_i) = 0$. (14)

In our applications, minimal faces are vertices and the above condition becomes:

If \bar{x} is a vertex of $\operatorname{conv}(X)$, then for each $i \in N$, $f(\bar{x}_i) = f_j$ for some $f_j \in \mathcal{F}$.

Since I is nonempty, every complete list \mathcal{F} must include the value 0, thus $f_k = 0$.

We now consider a mixed-integer set $MIX^{DN} = \{x : Ax \ge b; x_i \text{ integer}, i \in I\}$, where A is a dual network matrix. That is, the system $Ax \ge b$ is constituted by inequalities of the type (3)–(5). We assume that we are given a list $\mathcal{F} = \{f_1 > f_2 \cdots > f_k\}$ which is complete for MIX^{DN} . In order to obtain an extended formulation for $conv(MIX^{DN})$, we consider the following mixed-integer set:

$$x_i = \mu^i + \sum_{\ell=1}^k f_\ell \delta^i_\ell, \quad i \in N$$

$$\tag{15}$$

$$\sum_{\ell=1}^{k} \delta_{\ell}^{i} = 1, \ \delta_{\ell}^{i} \ge 0, \quad i \in N, \ell \in K$$

$$\tag{16}$$

$$\delta^i_{\ell} = 0, \qquad i \in I, \, \ell \in K \setminus \{k\} \tag{17}$$

$$x_i - x_j \ge l_{ij}, \qquad (i,j) \in N^e \tag{18}$$

$$x_i > l_i, \qquad i \in N^l \tag{19}$$

$$x_i \le u_i, \qquad i \in N^u \tag{20}$$

$$\mu^i$$
 integer, δ^i_ℓ integer, $i \in N, \ell \in K$, (21)

where inequalities (18)–(20) constitute the system $Ax \ge b$.

Let $MIX^{\mathcal{F}}$ be the set of vectors x such that there exist $\mu^i, \delta^i_{\ell}, i \in N, \ell \in K$ satisfying the above constraints. Note that equations (17) force variables $x_i, i \in I$ to be integer valued in $MIX^{\mathcal{F}}$.

Lemma 6 conv $(MIX^{DN}) = conv(MIX^{\mathcal{F}}).$

Proof: If $\bar{x} \in MIX^{\mathcal{F}}$ then \bar{x} satisfies the system $Ax \geq b$ (i.e. the inequalities (18)–(20)). Furthermore equations (17) force $x_i, i \in I$ to be integer. So $\bar{x} \in MIX^{DN}$. This shows $MIX^{\mathcal{F}} \subseteq MIX^{DN}$ and therefore $\operatorname{conv}(MIX^{\mathcal{F}}) \subseteq \operatorname{conv}(MIX^{DN})$.

To prove the reverse inclusion, we show that all rays and minimal faces of $\operatorname{conv}(MIX^{DN})$ belong to $\operatorname{conv}(MIX^{\mathcal{F}})$. If \bar{x} is a ray of $\operatorname{conv}(MIX^{DN})$ then the vector defined by

$$x_i = \bar{x}_i, \ \mu_i = \bar{x}_i, \ \delta^i_\ell = 0, \ i \in N, \ \ell \in K$$

is a ray of the polyhedron which is the convex hull of the vectors satisfying (15)–(21). This implies that \bar{x} is a ray of conv($MIX^{\mathcal{F}}$).

Since the list \mathcal{F} is complete, every minimal face F of $\operatorname{conv}(MIX^{DN})$ contains a point $\overline{x} \in MIX^{\mathcal{F}}$. Furthermore F is an affine subspace which can be expressed as $\{x : x = \overline{x} + \sum_{t=1}^{h} \lambda_t r_t, \lambda_t \in \mathbb{R}\}$ for some subset of rays r_1, \ldots, r_h of $\operatorname{conv}(MIX^{DN})$. Since $\overline{x} \in MIX^{\mathcal{F}}$ and r_1, \ldots, r_h are all rays of $\operatorname{conv}(MIX^{\mathcal{F}})$, then $F \subseteq \operatorname{conv}(MIX^{\mathcal{F}})$. \Box

Applying the unimodular transformation (7), inequalities (15)–(16) become inequalities (8)–(9), while inequalities (18)–(20) become inequalities (10)–(13). Let Q be the polyhedron on the space of the variables $\{(x_i, \mu_{\ell}^i), i \in N, \ell \in K \cup \{0\}\}$ defined by the inequalities (8)–(13) corresponding to inequalities (15), (16), (18), (19), (20) under transformation (7) and let Q^I be the face of Q defined by equations

$$\mu_{\ell}^{i} - \mu_{\ell-1}^{i} = 0, \ i \in I, \ \ell \in K \setminus \{k\},$$
(22)

which are equivalent to equations (17) under transformation (7).

Theorem 7 The polyhedron $conv(MIX^{DN})$ is the projection onto the space of the x-variables of the face Q^I of Q.

Proof: Theorem 5 shows that every minimal face of Q contains a vector $(\bar{x}, \bar{\mu})$ with integral $\bar{\mu}$. So the same holds for Q^I , which is a face of Q. By applying the transformation which is the inverse of (7), this shows that every minimal face of the polyhedron defined by (15)–(20) contains a point $(\bar{x}, \bar{\mu}, \bar{\delta})$ where $(\bar{\mu}, \bar{\delta})$ is integral. So the projection of this polyhedron onto the *x*-space coincides with conv $(MIX^{\mathcal{F}})$ and by Lemma 6 we are done.

We now consider a mixed-integer set $MIX^{2TU} = \{x : Ax \ge b; x_i \text{ integer}, i \in I\}$, where A is a TU matrix with at most two nonzero entries per row. By Corollary 2, A can be transformed into a dual network matrix by changing signs of some of its columns. Then MIX^{2TU} is transformed into a set of the type MIX^{DN} . Notice that if $\mathcal{F} = \{f_1 > \cdots > f_k\}$ is a list which is complete for MIX^{2TU} , then the list $\{0; f_\ell, 1 - f_\ell, 1 \le \ell < k\}$ is complete for the transformed set MIX^{DN} .

Then Theorem 7 has the following implication:

If a mixed-integer set MIX^{2TU} admits a complete list \mathcal{F} whose size is polynomial in the size of its description (given by the system $Ax \geq b$), the extended formulation of the corresponding set MIX^{DN} given by the inequalities that define Q^{I} is compact. Therefore the problem of optimizing a linear function over such sets MIX^{2TU} can be solved in polynomial time.

6 On the length of a complete list

We prove here the following result:

Theorem 8 In the set of vertices of polyhedron Q defined by the following set of inequalities:

$$\sigma_i + r_j \ge \frac{3^{(j-1)n+i}}{3^{n^2+1}}, \quad i, j \in N$$
(23)

$$\sigma_i \ge 0, \ r_j \ge 0, \qquad i, j \in N \tag{24}$$

the number of distinct fractional parts taken by variable σ_n is exponential in n.

Observation 1 Since the constraint matrix of inequalities (23)-(24) is a TU matrix with at most two nonzero entries per row, there exists a mixed-integer set M of the type MIX^{2TU} which is defined on continuous variables $\sigma_i, r_j, i, j \in N$ and integer variables $y_h, h \in I$ such that the polyhedron $\operatorname{conv}(M) \cap \{(\sigma, r, y) : y_h = 0, h \in I\}$ is a nonempty face of $\operatorname{conv}(M)$ described by inequalities (23)-(24). Therefore Theorem 8 shows that any extended formulation of $\operatorname{conv}(M)$ that explicitly takes into account a list of all possible fractional parts of the continuous variables will not be compact in the description of M.

Now let b_{ij} be as in the theorem, i.e. $b_{ij} = \frac{3^{(j-1)n+i}}{3^{n^2+1}}, i, j \in N$.

Observation 2 $b_{ij} < b_{i'j'}$ if and only if $(j,i) \prec (j',i')$, where \prec denotes the lexicographic order. Thus $b_{11} < b_{21} \cdots < b_{n1} < b_{12} < \cdots < b_{nn}$.

Lemma 9 (i) Suppose that $\alpha \in \mathbb{Z}_+^q$ with $\alpha_t < \alpha_{t+1}$ for $1 \leq t \leq q-1$, and $\Phi(\alpha) = \sum_{t=1}^q (-1)^{q-t} 3^{\alpha_t}$. Then $\frac{3}{2} 3^{\alpha_q} > \Phi(\alpha) > \frac{1}{2} 3^{\alpha_q}$.

(ii) Suppose that α is as above and $\beta \in \mathbb{Z}_{+}^{q'}$ is defined similarly. Then $\Phi(\alpha) = \Phi(\beta)$ if and only if $\alpha = \beta$.

Proof: (i) $\sum_{t=0}^{\alpha_q-1} 3^t = \frac{3^{\alpha_q}-1}{3^{-1}} < \frac{1}{2} 3^{\alpha_q}$. Now $\Phi(\alpha) > 3^{\alpha_q} - \sum_{t=1}^{\alpha_q-1} 3^t > 3^{\alpha_q} - \frac{1}{2} 3^{\alpha_q} = \frac{1}{2} 3^{\alpha_q}$, and $\Phi(\alpha) < 3^{\alpha_q} + \sum_{t=1}^{\alpha_q-1} 3^t < 3^{\alpha_q} + \frac{1}{2} 3^{\alpha_q} = \frac{3}{2} 3^{\alpha_q}$.

(ii) Suppose $\alpha \neq \beta$. Wlog we assume $q \geq q'$. Assume first $(\alpha_{q-q'+1}, \ldots, \alpha_q) = \beta$. Then q > q'(otherwise $\alpha = \beta$) and, after defining $\bar{\alpha} = (\alpha_1, \ldots, \alpha_{q-q'})$, we have $\Phi(\alpha) - \Phi(\beta) = \Phi(\bar{\alpha}) > 0$ by (i). Now assume $(\alpha_{q-q'+1}, \ldots, \alpha_q) \neq \beta$. Define $h = \min\{\tau : \alpha_{q-\tau} \neq \beta_{q'-\tau}\}$ and suppose $\alpha_{q-h} > \beta_{q'-h}$ (the other case is similar). If we define the vectors $\bar{\alpha} = (\alpha_1, \ldots, \alpha_{q-h})$ and $\bar{\beta} = (\beta_1, \ldots, \beta_{q'-h})$, (i) gives $\Phi(\alpha) - \Phi(\beta) = \Phi(\bar{\alpha}) - \Phi(\bar{\beta}) > \frac{1}{2}3^{\alpha_{q-h}} - \frac{3}{2}3^{\beta_{q'-h}} \geq 0$, as $\alpha_{q-h} > \beta_{q'-h}$.

We now give a construction of an exponential family of vertices of Q such that at each vertex variable σ_n takes a distinct fractional part. Therefore this construction proves Theorem 8.

Let (i_1, \ldots, i_m) and (j_1, \ldots, j_{m-1}) be two increasing subsets of N with $i_1 = 1$ and $i_m = n$. For $i, j \in N$, let $p(i) = \max\{t : i_t \leq i\}$ and $q(j) = \max\{t : j_t \leq j\}$, with q(j) = 0 if $j < j_1$.

Consider the following system of equations:

$$\begin{aligned} \sigma_{i_1} &= 0\\ \sigma_{i_t} + r_{j_t} &= b_{i_t j_t}, \quad 1 \le t \le m - 1\\ \sigma_{i_{t+1}} + r_{j_t} &= b_{i_{t+1} j_t}, \quad 1 \le t \le m - 1\\ \sigma_{i_{q(j)+1}} + r_j &= b_{i_{q(j)+1} j}, \; j \notin \{j_1, \dots, j_{m-1}\}\\ \sigma_i + r_{j_{p(i)}} &= b_{i j_{p(i)}}, \quad i \notin \{i_1, \dots, i_m\}. \end{aligned}$$

The unique solution of this system is:

$$\begin{aligned} \sigma_{i_1} &= 0\\ \sigma_{i_t} &= \sum_{\ell=1}^{t-1} b_{i_{\ell+1}j_{\ell}} - \sum_{\ell=1}^{t-1} b_{i_{\ell}j_{\ell}}, \ 2 \le t \le m\\ r_{j_t} &= \sum_{\ell=1}^{t} b_{i_{\ell}j_{\ell}} - \sum_{\ell=1}^{t-1} b_{i_{\ell+1}j_{\ell}}, \ 1 \le t \le m-1\\ \sigma_i &= b_{ij_{p(i)}} - r_{j_{p(i)}}, \qquad i \notin \{i_1, \dots, i_m\}\\ r_j &= b_{i_{q(j)+1}j} - \sigma_{i_{q(j)+1}}, \qquad j \notin \{j_1, \dots, j_{m-1}\} \end{aligned}$$

As each of these variables σ_i, r_j takes a value of the form $\Phi(\alpha)/3^{n^2+1}$, by Lemma 9 (i) we have that $\sigma_{i_t} > \frac{1}{2}b_{i_tj_{t-1}} > 0$ for $2 \le t \le m$, $r_{j_t} > \frac{1}{2}b_{i_tj_t} > 0$ for $1 \le t \le m-1$, $\sigma_i > \frac{1}{2}b_{i_j} > 0$ for $i \notin \{i_1, \ldots, i_m\}$, and $r_j > \frac{1}{2}b_{i_q(j)+1j} > 0$ for $j \notin \{j_1, \ldots, j_{m-1}\}$. Therefore the nonnegativity constraints are satisfied.

Now we show that the other constraints are satisfied. Consider the i, j constraint with $j \notin \{j_1, \ldots, j_{m-1}\}$. We distinguish some cases.

- 1. $p(i) \le q(j)$. Then $\sigma_i + r_j \ge r_j > \frac{1}{2}b_{i_{q(j)+1}j} \ge \frac{1}{2}b_{i_{p(i)+1}j} \ge \frac{3}{2}b_{ij} > b_{ij}$.
- 2. p(i) > q(j) and $i \notin \{i_1, \ldots, i_m\}$. Then $\sigma_i + r_j \ge \sigma_i > \frac{1}{2}b_{ij_{p(i)}} \ge \frac{1}{2}b_{ij_{q(j)+1}} \ge \frac{3}{2}b_{ij} > b_{ij}$.
- 3. p(i) = q(j) + 1 and $i = i_t$ for some $1 \le t \le m$ (thus p(i) = t = q(j) + 1). In this case the i, j constraints is satisfied at equality by construction.
- 4. p(i) > q(j) + 1 and $i = i_t$ for some $1 \le t \le m$ (thus p(i) = t > q(j) + 1). Then $\sigma_i + r_j \ge \sigma_i > \frac{1}{2} b_{ij_{t-1}} \ge \frac{1}{2} b_{ij_{q(j)+1}} \ge \frac{3}{2} b_{ij} > b_{ij}$.

The argument with $i \notin \{i_1, \ldots, i_m\}$ is similar.

Finally suppose that $i = i_t$ and $j = j_u$ with $u \notin \{t-1, t\}$. If u > t, $\sigma_i + r_j \ge r_j > \frac{1}{2}b_{i_u j_u} \ge \frac{3}{2}b_{i_t j_u} > b_{ij}$. If u < t-1, $\sigma_i + r_j \ge \sigma_i > \frac{1}{2}b_{i_t j_{t-1}} \ge \frac{3}{2}b_{i_t j_u} > b_{ij}$. This shows that the solution is feasible and as it is unique, it defines a vertex of the above

This shows that the solution is feasible and as it is unique, it defines a vertex of the above polyhedron.

Now let $a_{ij} = (j-1)n + i$, so that $b_{ij} = 3^{a_{ij}}/3^{n^2+1}$ and take

$$\alpha = (a_{i_1j_1}, a_{i_2j_1}, \dots, a_{i_mj_1}, a_{i_1,j_2}, \dots, a_{i_mj_{m-1}}).$$

As $\sigma_n = \Phi(\alpha)/3^{n^2+1}$, it follows from Lemma 9 (ii) that in any two vertices constructed as above by different sequences (i_1, \ldots, i_m) , (j_1, \ldots, j_{m-1}) and $(i'_1, \ldots, i'_{m'})$, $(j'_1, \ldots, j'_{m'-1})$, the values of σ_n are distinct numbers in the interval (0, 1). As the number of such sequences is exponential in n, this proves Theorem 8.

We now describe conditions that ensure the existence of a complete list for a mixed-integer set MIX^{2TU} which is compact. Since X is described by a linear system $Ax \ge b$ where A is a TU matrix with at most two nonzero entries per row, the constraints defining X are of the following type:

$$x_i + x_j \ge l_{ij}^{++}, \quad (i,j) \in N^{++}$$
(25)

$$x_i - x_j \ge l_{ij}^{+-}, \quad (i,j) \in N^{+-}$$
 (26)

$$-x_i - x_j \ge l_{ij}^{--}, \quad (i,j) \in N^{--}$$
(27)

$$x_i \ge l_i, \qquad i \in N^l$$

$$x_i \le u_i, \qquad i \in N^u$$

$$x_i$$
 integer, $i \in I$

where $N^{++}, N^{+-}, N^{--} \subseteq N \times N$ and $N^l, N^u, I \subseteq N$. Wlog we assume that if $(i, j) \in N^{++}$ then $(j, i) \notin N^{++}$ and if $(i, j) \in N^{--}$ then $(j, i) \notin N^{--}$.

Let $G_X = (V, E)$ be the undirected graph with node set $V = L = N \setminus I$ corresponding to the continuous variables of X. E contains an edge ij for each inequality of the type (25)–(27) with $i, j \in L$ appearing in the linear system that defines X. Notice that since A is a TU matrix, then, for fixed i, j, the system $Ax \ge b$ can contain either inequalities of type (26) or inequalities of type (25),(27), but not both. Therefore, for each pair of nodes i, j in V, E contains at most two parallel edges connecting i and j.

We impose a *bi-orientation* ω on G_X : to each edge $e \in E$ (corresponding to an inequality $a_i x_i + a_j x_j \geq l_{ij}$) and each endnode *i* of *e*, we associate the value $\omega(e, i) = tail$ if $a_i = 1$, the value $\omega(e, i) = head$ otherwise. Thus each edge of *G* could have one head and one tail (if corresponding to an inequality (26)), two tails (if corresponding to an inequality (25)) or two heads (if corresponding to an inequality (27)).

Given a path $P = (v_0, e_1, v_1, e_1, \ldots, v_t)$ in G_X , where $v_0, \ldots, v_t \in V$ and $e_1, \ldots, e_t \in E$, we want to define the ω -length of P, $l_{\omega}(P)$. To do this, we first define the *reverse* of an edge $e \in E$ as the edge obtained by turning each head (resp. tail) of e into a tail (resp. head).

We construct a path $P' = (v_0, e'_1, v_1, e'_1, \dots, v_t)$ from P by reversing some edges, so that v_0 is a tail of e_1 , and every node $v_j, 1 \leq j < t$ is a head of one edge of P' and a tail of the other. Note that given P, the path P' is unique.

Now we define $l_{\omega}(P) = \sum_{j=1}^{t} \varepsilon(P, e_j) l_{e_j}$, where l_e is the right-hand-side of the inequality corresponding to edge e and

$$\varepsilon(P, e_j) = \begin{cases} -1 & \text{if } e_j \text{ has been reversed in } P' \\ +1 & \text{otherwise.} \end{cases}$$

We also define the list $\mathcal{G} = \{g_1, \ldots, g_\ell\}$ as the set of values $f(l_\omega(P))$ for all paths P in G_X .

Theorem 10 Let X be a mixed-integer set of the type MIX^{2TU} and define \mathcal{G} as above. Then X admits a list which is complete whose length is $\mathcal{O}(m\ell)$, where m is the number of inequalities in the description of X and $\ell = |\mathcal{G}|$.

Proof: Let = (\bar{x}_L, \bar{x}_I) be a vertex of conv(X). Then \bar{x}_L is a vertex of the polyhedron defined by the inequalities:

$$a_i x_i + a_j x_j \ge l_{ij}^{**} \quad (i,j) \in N^{**}, \, i,j \in L$$
(28)

$$a_i x_i \ge l_{ij}^{**} - a_j \bar{x}_j \quad (i,j) \in N^{**}, \, i \in L, \, j \in I$$

$$\tag{29}$$

$$a_j x_j \ge l_{ij}^{**} - a_i \bar{x}_i \quad (i,j) \in N^{**}, \, i \in I, \, j \in L$$
(30)

$$x_i > l_i \qquad i \in L \cap N^\ell \tag{31}$$

$$x_i \le u_i \qquad i \in L \cap N^u, \tag{32}$$

where if the original inequality is of type (25), then $a_i = a_j = 1$ and ** stands for ++, and the other cases are defined accordingly.

Let $S_{\bar{x}}$ be a set of |L| independent inequalities among (28)–(32) that define \bar{x}_L . Then it is well known (and easy to see) that the edges corresponding to inequalities of type (28) in $S_{\bar{x}}$ define a forest $F_{\bar{x}}$ in G_X . Let $C_{\bar{x}} = (V(C_{\bar{x}}), E(C_{\bar{x}}))$ be a connected component of such a forest. Since $|V(C_{\bar{x}})| = |E(C_{\bar{x}})| + 1$, $C_{\bar{x}}$ contains a unique "root" node r whose value is determined by one of the bounds (29)–(32) and therefore the fractional part of \bar{x}_r takes $\mathcal{O}(m)$ possible values, where m is the number of inequalities in the description of X.

If v is a node of $C_{\bar{x}}$ distinct from r, then the value of \bar{x}_v is determined by the value of \bar{x}_r and the tight inequalities (28) corresponding to the edges in the path P_{vr} in $C_{\bar{x}}$ having v as first vertex and r as last vertex: if e is the edge in P_{vr} incident with r and if P'_{vr} is constructed from P_{vr} as described above, we have

$$\bar{x}_{v} = \begin{cases} l_{\omega}(P_{vr}) + \bar{x}_{r} & \text{if } r \text{ is a head of } e \\ l_{\omega}(P_{vr}) - \bar{x}_{r} & \text{otherwise.} \end{cases}$$
(33)

Since the list \mathcal{G} has ℓ elements, this shows that the fractional part of each variable \bar{x}_v at a vertex can take at most $\mathcal{O}(m\ell)$ values.

Corollary 11 Assume that a mixed-integer set X of the type MIX^{2TU} satisfies at least one of the following conditions:

- (i) The number of paths connecting two nodes in G_X is bounded by a polynomial function of the size of the description of X;
- (ii) The number of elements in the sets $\{f(l_{ij}^{**}), (i, j) \in N^{**}\}$, where $** \in \{++, +-, --\}$, is bounded by a constant.
- (iii) G_X is bipartite with vertex classes U, V and the inequalities defining X which contain two continuous variables x_u, x_v ($u \in U, v \in V$) have the form $x_u + x_v \ge b_v - b_u$ for some vector b with indices in $U \cup V$.

Then X admits a complete list of fractional parts which is compact.

Proof: If (i) holds, the length of the list \mathcal{G} is bounded by a polynomial function. Then Theorem 10 implies that there is a complete list for X which is compact.

Now suppose that (ii) holds and assume

$$\bigcup_{* \in \{++,+-,--\}} \{ f(l_{ij}^{**}), (i,j) \in N^{**} \} = \{ f_1, \dots, f_t \}$$

Each value $l_{\omega}(P_{rv})$ can be expressed as

$$l_{\omega}(P_{rv}) = \sum_{h=1}^{t} \alpha_h f_h,$$

where α_h is an integer for all h. Since G_X has |L| nodes, the maximum length of a path in G_X is |L|-1. This implies $|\alpha_h| \leq |L|-1$ for all h. Then the length of the list \mathcal{G} is at most $(2|L|-1)^t$. Thus, by Theorem 10 there is a complete list for X of size $\mathcal{O}(m(2|L|-1)^t) = \mathcal{O}(mn^t)$, as t is a constant.

Finally assume that (iii) holds. In this case it is easy to verify that for $v \in U \cup V$,

$$l_{\omega}(P_{vr}) = b_r - b_v \tag{34}$$

and thus X admits a complete list which is compact.

Observation 3 The example whose complete list has exponential length constructed in Theorem 8 shows that if a mixed-integer set of the type MIX^{2TU} does not satisfy any of the above three conditions, then its complete list may be long.

Observation 4 If X is a mixed-integer set of the type MIX^{2TU} such that the size of all connected components of G_X is bounded by a constant, then X satisfies condition (i) of the above Corollary.

7 Examples

We show that several well-studied mixed-integer sets can be transformed into sets of the type MIX^{2TU} , but first we give a precise meaning to the word "transformed".

7.1 Mixed-integer linear mappings

Theorem 12 Consider the transformation defined by $\binom{x'}{y'} = A\binom{x}{y}$, where $(x, y) \in \mathbb{R}^{m+n}$, $(x', y') \in \mathbb{R}^{m'+n'}$, m + n = m' + n' and $A \in \mathbb{R}^{(m+n) \times (m'+n')}$ is nonsingular. The following are equivalent:

(i) For each $(x,y) \in \mathbb{R}^{m+n}$, y is integral if and only if y' is integral.

(ii)
$$m = m', n = n' \text{ and } A = \begin{bmatrix} A_1 & A_2 \\ \mathbf{0} & U \end{bmatrix}$$
, where $A_1 \in \mathbb{R}^{m \times m}$ is nonsingular, $A_2 \in \mathbb{R}^{m \times n}$ and $U \in \mathbb{R}^{n \times n}$ is unimodular.

Proof: (i) \Rightarrow (ii) Suppose $A = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix}$, where $A_1 \in \mathbb{R}^{m' \times m}$, $A_2 \in \mathbb{R}^{m' \times n}$, $A_3 \in \mathbb{R}^{n' \times m}$ and $A_4 \in \mathbb{R}^{n' \times n}$. If $A_3 \neq \mathbf{0}$, one of its entries is a nonzero number a. Wlog we assume that this entry is in the first row and first column of A_3 . Then $A \begin{pmatrix} e_1/2a \\ \mathbf{0} \end{pmatrix}$ contains a component equal to 1/2 in the entry corresponding to y'_1 , contradicting (i). Thus $A_3 = \mathbf{0}$.

If $B = \begin{bmatrix} B_1 & B_2 \\ B_3 & B_4 \end{bmatrix}$ is the inverse of $A (B_1 \in \mathbb{R}^{m \times m'}, B_2 \in \mathbb{R}^{m \times n'}, B_3 \in \mathbb{R}^{n \times m'}$ and $B_4 \in \mathbb{R}^{n \times n'})$, a similar argument shows that $B_3 = \mathbf{0}$.

Thus we obtain $y' = A_4 y$, $y = B_4 y'$ for each y. We now prove that this implies n = n'. Equation $y = B_4 A_4 y$ for all y yields $B_4 A_4 = I_n$, thus $rkA_4 \ge n$. Since A_4 is $n' \times n$, this implies $n' \ge n$. Similarly, starting from $y' = A_4 B_4 y'$ for all y', one obtains $n \ge n'$. Thus n = n' and consequently m = m'. (i) then implies that A_4 is unimodular. (ii) \Rightarrow (i) The transformation and its inverse are

$$\begin{cases} x' = A_1 x + A_2 y \\ y' = U y \end{cases} \text{ and } \begin{cases} x = A_1^{-1} (x' - A_2 U^{-1} y') \\ y = U^{-1} y' \end{cases}$$

Since U is unimodular, these two transformations preserve the integrality of y and y'. \Box

Consider an arbitrary mixed-integer set $X = \{x : Ax \ge b; x_i \text{ integer}, i \in I\}$ and let \mathcal{F} be a complete list of fractional parts which is compact for X. In general, if we apply a linear mapping of the kind described in Theorem 12 to X, the transformed mixed-integer set X' may not have a complete list which is compact. For instance, let $X = \{x : 0 \le x_i \le 2^{-i}, i \in N\}$ (so here $I = \emptyset$; similar examples with $I \ne \emptyset$ can be easily derived from this example). The list $\mathcal{F} = \{0; 2^{-i}, i \in N\}$ is complete for X and its size is linear in the size of the description of X. The linear mapping $x'_1 = x_2 + \cdots + x_n, x'_i = x_i, i \in N \setminus \{1\}$, transforms X into $X' = \{x' : 0 \le x'_1 - x'_2 - \cdots - x'_n \le 2^{-1}; 0 \le x'_i \le 2^{-i}, i \in N \setminus \{1\}$. Now, for each subset $S \subseteq N \setminus \{1\}$ the vector

$$x'_i = \begin{cases} 2^{-i} & \text{if } i \in S \\ 0 & \text{if } i \in (N \setminus \{1\}) \setminus S \\ \sum_{j \in S} 2^{-j} & \text{if } i = 1 \end{cases}$$

is a vertex of X'. Since the values of the sum $\sum_{j \in S} 2^{-j}$ are distinct numbers in the interval [0,1) for each S, any complete list for X' contains a number of fractional parts which is exponential in the size of the description of X.

However, for the mixed-integer sets we study below (except the sets INT in Section 7.3 and BIP(I, L) in Section 7.5), we will consider linear mappings of the kind of Theorem 12 which give rise to mixed-integer sets of the type MIX^{2TU} satisfying at least one of the conditions of Corollary 11. Thus, in these cases the existence of a complete list which is compact is guaranteed. Furthermore, for some of these sets a complete list which is compact is explicitly given.

7.2 The continuous mixing set with flows

The continuous mixing set with flows CFLOWMIX, studied in Conforti et al. [2], is

$$s + r_j + x_j \ge b_j, \qquad j \in N$$
$$x_j \le y_j, \qquad j \in N$$
$$s \ge 0, r_j \ge 0, x_j \ge 0, y_j \ge 0 \text{ integer}, \quad j \in N.$$

As explained in [2], this set provides both a relaxation of the single item constant capacity lot-sizing problem with backlogging and an exact formulation of the two stage stochastic lot-sizing problem with constant capacities and backlogging.

The following observation shows that the above mixed-integer set can be transformed into a set of the type MIX^{2TU} . Let FLOW be the following set:

$$\sigma_j + x_j \ge b_j, \qquad j \in N$$
$$x_j \le y_j, \qquad j \in N$$
$$s \ge 0, \ \sigma_j - s \ge 0, \ x_j \ge 0, \ y_j \ge 0 \text{ integer}, \quad j \in N.$$

Since the constraint matrix of the above system is a TU matrix with at most two nonzero entries per row, FLOW is a mixed-integer set of the type MIX^{2TU} .

Observation 5 The linear transformation:

$$s = s, \ \sigma_j = s + r_j, \ x_j = x_j, \ y_j = y_j, \ j \in N$$

maps CFLOWMIX into FLOW.

Remark that if X is a mixed-integer set of the type FLOW, then the graph G_X (as defined in Section 6) is a tree, with leaves corresponding to variables x_j . Therefore G_X satisfies condition (i) of Corollary 11. Below we explicitly give a complete list for conv(FLOW) which is compact.

Lemma 13 The list $\mathcal{F} = \{0; f(b_i), j \in N; f(b_i - b_i), i, j \in N\}$ is complete for FLOW.

Proof: For a connected component $C_{\bar{x}}$ of $F_{\bar{x}}$, the root r corresponds to a variable which assumes an integer value. Then, by equation (33) we only need to compute the values $f(l_{\omega}(P))$ for all P in G_X . It is easy to check that the list $\mathcal{F} = \{0; f(b_j), j \in N; f(b_i - b_j), i, j \in N\}$ includes all these values.

Therefore the result of Section 5 provides an extended formulation of the set FLOW which is compact. Applying the inverse of the above linear transformation gives an extended formulation of CFLOWMIX which is compact.

We now introduce several faces of the polyhedron $\operatorname{conv}(CFLOWMIX)$ that have been studied.

7.2.1 The continuous mixing set

The continuous mixing set is the mixed-integer set CMIX defined as follows:

$$s + r_j + y_j \ge b_j, \qquad j \in N$$

$$s \ge 0, r_j \ge 0, y_j \ge 0 \text{ integer}, \quad j \in N.$$

Clearly the polyhedron $\operatorname{conv}(CMIX)$ is the face of $\operatorname{conv}(CFLOWMIX)$ defined by the equations $x_j = y_j, j \in N$. An extended formulation for $\operatorname{conv}(CMIX)$ which is compact was given by Miller and Wolsey [11]. Later Van Vyve [17] gave a more compact extended formulation and a linear inequality description of $\operatorname{conv}(CMIX)$ in the original space.

7.2.2 The mixing set with flows

The mixing set with flows FLOWMIX is defined as follows:

$$s + x_j \ge b_j, \qquad j \in N$$
$$x_j \le y_j, \qquad j \in N$$
$$s \ge 0, \ x_j \ge 0, \ y_j \ge 0 \text{ integer}, \quad j \in N.$$

The polyhedron $\operatorname{conv}(FLOWMIX)$ is the face of $\operatorname{conv}(CFLOWMIX)$ defined by the equations $r_j = 0, j \in N$. Conforti et al. [1] described $\operatorname{conv}(FLOWMIX)$ both with an extended formulation and in the original (s, x, y)-space.

7.2.3 The \geq -mixing set

The \geq -mixing set MIX^{\geq} is defined as follows:

$$s + y_j \ge b_j, \qquad j \in N$$

 $s \ge 0, y_j \ge 0$ integer, $j \in N.$

The polyhedron $\operatorname{conv}(MIX^{\geq})$ is the face of $\operatorname{conv}(FLOWMIX)$ defined by the equations $x_j = y_j, j \in \mathbb{N}$. Such sets were first studied explicitly by Günlük and Pochet [8].

The following observation shows that the \geq -mixing set admits a complete list that is shorter than that of the sets described above.

Observation 6 If (\bar{s}, \bar{y}) is a vertex of $\operatorname{conv}(MIX^{\geq})$, then $\bar{s} = 0$ or $f(\bar{s}) = f(b_j)$ for some $j \in N$. Therefore $\{0; f(b_j), j \in N\}$ is a complete list for MIX^{\geq} .

7.3 The intersection set

The intersection set INT, discussed in Conforti et al. [2], is defined as follows:

$$\sigma_i + r_j + y_j \ge b_{ij}, \qquad i, j \in N$$

$$\sigma_i \ge 0, \ r_j \ge 0, \ y_j \ge 0 \text{ integer}, \quad i, j \in N.$$

Observation 7 The linear transformation:

$$y_j = y_j, \ \sigma_i = \sigma_i, \ \rho_j = r_j + y_j, \ i, j \in N$$

maps INT into the following mixed-integer set:

$$\sigma_i + \rho_j \ge b_{ij}, \qquad i, j \in N$$

$$\rho_j - y_j \ge 0, \qquad j \in N$$

$$\sigma_i \ge 0, \ y_j \ge 0 \ integer, \quad i, j \in N.$$

The above mixed-integer set is of the type MIX^{2TU} .

In Section 6 it has been shown that in general the set INT does not admit a complete list \mathcal{F} whose size is polynomial in the size of the description of INT (see Observation 1).

7.4 Lot-sizing

Van Vyve [18] showed that the set LOT

$$s_i + r_j + \sum_{u=i}^{j} y_u \ge b_j - b_i, \quad i, j \in N, j > i$$

$$s_i \ge 0, r_j \ge 0, y_j \in \{0, 1\}, \quad i, j \in N$$

represents the dominant of the feasible solutions of a lot-sizing problem with constant capacities and backlogging, and provides an extended formulation for conv(LOT) which is compact.

Observation 8 The linear transformation:

$$z_0 = 0, \ z_j = \sum_{u=1}^{j} y_u, \ \sigma_i = s_i - z_{i-1}, \ \rho_j = r_j + z_j, \ i, j \in N$$
(35)

maps LOT into the following mixed-integer set:

$$\sigma_{i} + \rho_{j} \geq b_{j} - b_{i}, \quad i, j \in N, j > i$$

$$\sigma_{i} + z_{i-1} \geq 0, \quad i \in N$$

$$\rho_{j} - z_{j} \geq 0, \quad j \in N$$

$$0 \leq z_{j} - z_{j-1} \leq 1, \quad j \in N$$

$$z_{j} \text{ integer}, \quad j \in N$$
(36)

The above mixed-integer set is of the type MIX^{2TU} .

Lemma 14 Let X be the above mixed-integer set. The list $\mathcal{F} = \{0; f(b_i - b_j), i, j \in N\}$ is complete for X.

Proof: Again we use the same notation as in the proof of Theorem 10. The graph G_X is bipartite with one vertex class corresponding to variables σ_i and the other corresponding to variables ρ_j . The structure of inequalities (36) shows that condition (iii) of Corollary 11 is satisfied. Since all other constraints have integer right-hand-side, the root r corresponds to a variable which assumes an integer value. Then, by equations (33) and (34), the list given above contains all possible fractional parts taken by the variables at a vertex.

By the above Lemma and the form of transformation (35), we immediately derive the following result, which was shown by Van Vyve [18]:

Observation 9 The list $\mathcal{F} = \{0; f(b_i - b_j), i, j \in N\}$ is complete for LOT.

The above observation, together with the result of Section 5, provides an extended formulation of LOT which is compact.

7.5 Bipartite cover inequalities

Given a bipartite graph G = (U, V; E), let (I, L) be a partition of $U \cup V$ with $I \neq \emptyset$ and let BIP(I, L) be the mixed-integer set:

$$\begin{aligned} x_u + x_v &\geq b_{uv}, \quad uv \in E \\ x_u &\geq 0, \qquad u \in L \\ x_u &\geq 0 \text{ integer}, \quad u \in I. \end{aligned}$$

The set BIP(I, L) is obviously a set of the type MIX^{2TU} . The example of Section 6 shows that BIP(I, L) does not admit in general a complete list which is compact. However, such a list exists in the following two special cases.

The first case is the set BIP(U, V) (i.e. the integer variables correspond to the nodes of one side of the bipartition of G): Miller and Wolsey [11] show that for the set BIP(U, V)the list $\{0; f(b_{uv}), uv \in E\}$ is complete and they also give a formulation of BIP(U, V) in the *x*-space.

The second case is the set BIP(I, L) with the additional condition that $2b_{uv}$ is integer for all $uv \in E$, that is, $f(b_{uv})$ is either 0 or 1/2 for all $uv \in E$: this set satisfies condition (ii) of Corollary 11. Conforti et al. [3] give a formulation in the x-space of this set.

8 Concluding Remarks

One outstanding question that remains concerns the complexity of the optimization problem over the sets MIX^{2TU} when the list of fractional parts has exponential size. More specifically, whether the polyhedron conv (MIX^{2TU}) admits an extended formulation which is compact, even when the list of fractional parts has exponential size.

Another intriguing challenge is to understand under what conditions the formulation for $\operatorname{conv}(MIX^{2TU})$ in the original x-space can be explicitly described (possibly by projecting the extended formulation introduced in this paper). A fundamental result of this type is the

formulation of $\operatorname{conv}(MIX^{\geq})$ in the original space of Günlük and Pochet [8]. Other results for bipartite cover inequalities (i.e. for $\operatorname{conv}(BIP(I, L))$) can be found in [3] and [11]. Van Vyve [17] gives the formulation for $\operatorname{conv}(CMIX)$, Conforti et al. [1] give the formulation for $\operatorname{conv}(FLOWMIX)$. To the best of our knowledge, this is what is known so far.

Another aspect is the fact that a set MIX^{2TU} is equivalent to a set MIX^{DN} and that the extended formulation introduced in this paper involves a system of inequalities $A(x, \mu) \geq b$ where A is a dual network matrix and b is an integral vector. The associated optimization problem can therefore be solved in the extended space as a dual of a network flow problem. Can this be used to develop new algorithms for optimization and/or separation? Computationally, what is the most effective use of the formulation for MIX^{2TU} , when the description of a set MIX^{2TU} is a relaxation of a more complicated mixed-integer set? Should one use the dual network formulation (9)–(13), the same formulation but with the δ variables as in (1)–(6) rather than the μ variables, cutting planes and separation, or other?

A last question concerns the extension of our model. Recently it has been shown that several problems that involve the optimization of a linear function over a generalization of the mixing set MIX^{\geq} , but whose description does not involve a TU matrix, are solvable in polynomial time. Two such sets are the mixing set with divisible capacities in Conforti and Wolsey [4] and the mixing-MIR set with divisible capacities (Van Vyve [16], de Farias and Zhao [5]). To what extent, if any, can the results here be extended to these problems?

References

- [1] M. Conforti, M. Di Summa and L. A. Wolsey, *The mixing set with flows*, submitted to SIAM Journal of Discrete Mathematics (2005).
- [2] M. Conforti, M. Di Summa and L. A. Wolsey, The continuous mixing set with flows, submitted to IPCO 2007 (2006).
- [3] M. Conforti, B. Gerards and G. Zambelli, *Mixed-integer vertex cover on bipartite graphs*, manuscript (2006).
- M. Conforti and L. A. Wolsey, Compact formulations as unions of polyhedra, CORE Discussion Paper 2005/62, August 2005.
- [5] I. de Farias and M. Zhao, *The mixing-MIR set with divisible capacities*, Report, University of Buffalo, September 2005 (revised November 2006).
- [6] S. Even, A. Itai, and A. Shamir, On the complexity of timetable and multicommodity flow problems, SIAM Journal on Computing, 5(4) (1976), 691–703.
- [7] A. Ghouila-Houri, Caractérisations des matrices totalement unimodulaires, Comptes Rendus de l'Académie des Sciences, 254 (1962), 1192–1194.
- [8] O. Günlük and Y. Pochet, *Mixing mixed-integer inequalities*, Mathematical Programming, 90 (2001), 429–457.
- [9] I. Heller and C. B. Tompkins, An extension of a theorem of Dantzig, in Linear Inequalities and Related Systems, H. W. Kuhn and A. W. Tucker eds., Princeton University Press (1956), 247–254.

- [10] B. Korte and J. Vygen. Combinatorial Optimization, volume 21 of Algorithms and Combinatorics, Springer-Verlag, Berlin, second edition, 2002.
- [11] A. Miller and L. A. Wolsey, Tight formulations for some simple MIPs and convex objective IPs, Mathematical Programming B, 98 (2003), 73–88.
- [12] G. L. Nemhauser and L. A. Wolsey, Integer and Combinatorial Optimization, Wiley Interscience, New York, 1988.
- [13] Y. Pochet and L. A. Wolsey, Polyhedra for lot-sizing with Wagner-Whitin costs, Mathematical Programming, 67 (1994), 297–324.
- [14] Y. Pochet and L. A. Wolsey, Production Planning by Mixed-Integer Programming, Springer Series in Operations Research and Financial Engineering, New York, 2006.
- [15] A. Schrijver, Theory of Linear and Integer Programming, Wiley, New York, 1986.
- [16] M. Van Vyve, A solution approach of production planning problems based on compact formulations for single-item lot-sizing models, Ph.D. thesis, Faculté des Sciences appliquées, Univiersité catholique de Louvain, Belgium, 2003.
- [17] M. Van Vyve, The continuous mixing polyhedron, Mathematics of Operations Research, 30 (2005), 441–452.
- [18] M. Van Vyve, Linear programming extended formulations for the single-item lot-sizing problem with backlogging and constant capacity, Mathematical Programming, 108 (2006), 53–78.