Global dynamics and imbalance effects in the Lucas-Uzawa model: further results[*]

R. Boucekkine[†]   B. Martínez[‡]   J. R. Ruiz-Tamarit[§]

CORE DISCUSSION PAPERS
2007/25

[†]Corresponding author. CORE and Department of Economics, Université Catholique de Louvain, Place Montesquieu 3, B-1348 Louvain-la-Neuve (Belgium). boucekkine@core.ucl.ac.be

[‡]Department of Economics, Universidad Complutense de Madrid. blmartin@ccee.ucm.es

[§]Universitat de València and Université catholique de Louvain. ramon.ruiz@uv.es

Abstract

In this paper we use a new analytical approach to the Lucas-Uzawa model (Boucekkine and Ruiz Tamarit, 2007) to extend the existing results on the dynamics, and notably on the imbalance effects arising in the model. The approach does not only allow to extend the traditional analysis to **any** initial conditions and for **all** variables in **level**, but it also permits a more general investigation of imbalance effects.

Keywords: Lucas-Uzawa, hypergeometric functions, imbalance effects, global dynamics.

Journal of Economic Literature: E20, O40, C60.

1 Introduction

The Lucas-Uzawa model has been at the heart of macroeconomic research for many decades, and it is still widely considered as a fundamental benchmark for ongoing research programs in many fields, notably in economic development. Two characteristics of the model makes it, however, nontrivial mathematically speaking: it is a two-sector model (with two controls and two state variables), which induces a much larger set of optimality conditions compared to the typical Ramsey model, and it is an endogenous growth model, and such models have the property of indeterminacy in the long-run variables' levels. A substantial part of the literature dealing with Lucas-Uzawa is precisely devoted to get through these problems. Important contributions in this topic are Caballé and Santos (1993), Xie (1994), Benhabib and Perli (1994) and Ortigueira (1998). None of this paper solves the model completely but they certainly allow to get an accurate picture of the mechanisms at work in the model. With the exception of Xie who solves explicitly a very special parametric case of the model, the other authors build on a transformed model with a lower dimension (3 against 4 in the original model) to overcome the problem of indeterminacy in levels. Typically, the (three) variables considered in the auxiliary models are the ratios physical to human capital and consumption to physical capital, and the fraction of human capital devoted to the final good sector. The same approach is taken in textbooks (see Barro and Sala-i-Martin, 1995, chapter 5).

Boucekkine and Ruiz-Tamarit (2007) propose a new method inspired from mathematical physics. Precisely, they show that the Lucas-Uzawa model can be explicitly solved for all variables in level using Gaussian hypergeometric functions. These solutions paths in levels have been shown to exhibit some specific non-monotonicities, a feature let in the dark in the traditional literature. However, the essential contribution of the paper is to supply the solution paths in closed form for any further exploration of the global dynamics of all the variables, a task which was considered as unrealistic for a long time. In this paper, we are aiming to show how the new approach can be advantageously used to dig deeper in the imbalance effects literature. A textbook presentation of it can be found in Barro and Sala-i-Martin (1995), chapter 5 (see also Mulligan and Sala-i-Martin, 1993).

Imbalance effects refer to the transition dynamics of a model when its state variables start below or above the corresponding long-run equilibrium value. The economy is initially out of equilibrium, and if the adequate stability conditions are met, it has to come back after a certain adjustment phase. Admittedly, such a topic is better appraised and more interesting in a global framework, that is, by allowing the economy to start arbitrarily far from equilibrium. Unfortunately, the traditional method is based on linearization around steady-states, which disqualify it for any global inspection.

In the Lucas-Uzawa model, the imbalance effect story has been quickly reduced to the transition dynamics of the model when the ratio physical to human capital stocks is initially below or above the corresponding long-run value. This might make sense. On the theoretical ground, however, very few papers have been devoted to clarify this point. Of course, this is largely due to the limitations imposed by the traditional method. Ortigueira (1998) is an exception. Extending in a way the previous work of Caballé and Santos (1993), he studied the imbalance effects in the Lucas-Uzawa model with the traditional method, and he shows in particular that in the *normal* parametric case[1], the human capital stock should *always* increase at a rate higher than the long-run counterpart

---

[1]We shall be very clear about the meaning of a normal parameterization in Section 4.

if the ratio physical to human capital stocks starts above the corresponding long-run value. That is, the initially scarce factor should be accumulated at a higher pace with respect to its long run balanced path. There are two important aspects in Ortigueira's analysis that could be easily improved within the new methodological set-up designed by Boucekkine and Ruiz-Tamarit. First of all, and at almost zero cost, the properties can be established for all variables in level, and for arbitrary initial conditions. Second, precisely thanks to the availability of all the solution paths in level and closed form, one can have a much more complete story of imbalance effects. Ortigueira restricts his analysis to the dynamics of human capital accumulation. What about physical capital? Suppose the economy starts with a ratio physical to human capital stocks above the corresponding long-run value. Then even though this ratio decreases monotonically to its long-run equilibrium value, physical capital can in principle either decrease or increase (at a rate lower than human capital) at least for some bounded time interval. Moreover, in the case the stock of physical grows from the beginning, there is no guarantee that it will grow at a rate lower than its long-run counterpart. Therefore, it is not clear at all *a priori* whether the stock of physical capital will have the same kind of behaviour as human capital, specially because, as established by Boucekkine and Ruiz-Tamarit (2007), such variable may exhibit non-monotonic paths in contrast to human capital stock. We will extend the theoretical analysis of imbalance effects to physical capital, and we will highlight an important asymmetry between physical and human capital, which is omitted in the related theoretical literature.

We shall clarify these issues in this paper. The next section reminds the main equations involved in the Lucas-Uzawa model. Section 3 summarizes the main properties of the closed-form solutions detected by Boucekkine and Ruiz-Tamarit. Section 4 revisits the imbalance effects properties with the new approach.

2   The optimal control problem

The problem is standard in economic growth (Lucas, 1988, for example). The economy is populated with many identical, rational agents, choosing the controls $c(t)$, consumption per capita, and $u(t) \, \forall t \geq t_0$, the fraction of non-leisure time devoted to goods production, which solve the dynamic optimization problem

$$max \int_0^\infty \frac{c(t)^{1-\sigma} - 1}{1 - \sigma} N(t) e^{-\rho t} dt \tag{1}$$

subject to

$$\overset{\bullet}{K}(t) = AK(t)^\beta (u(t) N(t) h(t))^{1-\beta} - \pi K(t) - N(t) c(t),$$

$$\overset{\bullet}{h}(t) = \delta (1 - u(t)) h(t) - \theta h(t),$$

$$K(0) = K_0, \quad h(0) = h_0, \quad N(0) = N_0,$$

$$c(t) \geqslant 0, \quad u(t) \in [0, 1], \quad K(t) \geqslant 0, \quad h(t) \geqslant 0.$$

The considered instantaneous utility function is standard, with $\sigma^{-1} > 0$ representing the constant elasticity of intertemporal substitution. Population at time t is $N(t)$, which is assumed to grow at a constant exogenously given rate n. Parameter ρ is the rate of time preference or discount rate. We assume $\rho > n$. $h(t)$ is the human capital level.

The output, $Y(t)$, which may be allocated to consumption or to physical capital accumulation depends on the capital stock, $K(t)$, and the effective work force, $u(t) N(t) h(t)$. Parameter β is the elasticity of output with respect to physical capital. The efficiency parameter A represents the constant technological level in the goods sector of this economy. The efficiency parameter δ represents the constant technological level in the educational sector. Both physical and human capital depreciate at constant rates, which are $\pi \geqslant 0$ and $\theta \geqslant 0$, respectively. We shall also assume that $\delta + n > \theta + \rho$ for positive (long run) growth to arise, as it will be transparent later.

The current value Hamiltonian associated with the previous intertemporal optimization problem is

$$H^c(K, h, \vartheta_1, \vartheta_2, c, u; A, \sigma, \beta, \delta, \pi, \theta, \{N(t) : t \geq 0\}) =$$

$$= \frac{c^{1-\sigma} - 1}{1 - \sigma} N + \vartheta_1 \left[AK^\beta (uNh)^{1-\beta} - \pi K - Nc \right] + \vartheta_2 \left[\delta (1 - u) h - \theta h \right], \tag{2}$$

where ϑ_1 and ϑ_2 are the co-state variables for K and h, respectively.

The first order necessary conditions are

$$c^{-\sigma} = \vartheta_1, \tag{3}$$

$$\vartheta_1 (1 - \beta) AK^\beta (uNh)^{-\beta} N = \vartheta_2 \delta, \tag{4}$$

the Euler equations

$$\dot{\vartheta_1} = (\rho + \pi) \vartheta_1 - \vartheta_1 \beta AK^{\beta-1} (uNh)^{1-\beta}, \tag{5}$$

$$\dot{\vartheta_2} = (\rho + \theta) \vartheta_2 - \vartheta_1 (1 - \beta) AK^\beta (uN)^{1-\beta} h^{-\beta} - \vartheta_2 \delta (1 - u), \tag{6}$$

the dynamic constraints

$$\dot{K} = AK^\beta (uNh)^{1-\beta} - \pi K - Nc, \tag{7}$$

$$\dot{h} = \delta (1 - u) h - \theta h, \tag{8}$$

the boundary conditions K_0, h_0, and the transversality conditions

$$\lim_{t \to \infty} \vartheta_1 K \exp\{-\rho t\} = 0, \tag{9}$$

$$\lim_{t \to \infty} \vartheta_2 h \exp\{-\rho t\} = 0. \tag{10}$$

From (3) and (4) we can express the control functions, c and u in terms of the other variables. These conditions also imply that, at any finite date, $\vartheta_1 \neq 0$ and $\vartheta_2 \neq 0$. After substituting these expressions into equations (5)-(8), we obtain the following four dimensional system, in terms of state and co-state variables only,

$$\dot{\vartheta_2} = -(\delta - \rho - \theta) \vartheta_2, \tag{11}$$

$$\dot{\vartheta_1} = (\rho + \pi) \vartheta_1 - \psi_1 (t) \vartheta_1^{\frac{1}{\beta}}, \tag{12}$$

$$\dot{K} = \psi_2 (t) K - \psi_3 (t), \tag{13}$$

$$\dot{h} = (\delta - \theta) h - \psi_4 (t), \tag{14}$$

4

where

$$\psi_1(t) = \beta A \left(\frac{(1-\beta) A}{\delta} \right)^{\frac{1-\beta}{\beta}} N^{\frac{1-\beta}{\beta}} \vartheta_2^{-\frac{1-\beta}{\beta}}, \tag{15}$$

$$\psi_2(t) = A \left(\frac{(1-\beta) A}{\delta} \right)^{\frac{1-\beta}{\beta}} N^{\frac{1-\beta}{\beta}} \left(\frac{\vartheta_1}{\vartheta_2} \right)^{\frac{1-\beta}{\beta}} - \pi, \tag{16}$$

$$\psi_3(t) = N \vartheta_1^{-\frac{1}{\sigma}}, \tag{17}$$

$$\psi_4(t) = \delta \left(\frac{(1-\beta) A}{\delta} \right)^{\frac{1}{\beta}} N^{\frac{1-\beta}{\beta}} \left(\frac{\vartheta_1}{\vartheta_2} \right)^{\frac{1}{\beta}} K. \tag{18}$$

These equations, together with the initial conditions, K_0 and h_0, and the transversality conditions (9) and (10) constitute the dynamic system which drives the economy over time. This dynamic system can be recursively solved in closed form. Boucekkine and Ruiz-Tamarit (2007) show that such a system can be solved explicitly without resorting to any dimension reduction. We summarize their results in the next section.

3 Explicit solutions

Boucekkine and Ruiz-Tamarit (2007) use Gaussian hypergeometric functions in their closed-form solution. Recall that the Gauss hypergeometric function (see Abramowitz and Stegun, 1972, or Temme, 1996), $_2F_1(a, b, c; z)$, with complex arguments a, b, c and z, is given by the series

$$_2F_1(a, b, c; z) = \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(c)_n} \frac{z^n}{n!},$$

where $(x)_n$ is the so-called Pochhammer symbol, defined by

$$(x)_n = \frac{\Gamma(x+n)}{\Gamma(x)},$$

where $\Gamma(.)$ is the special function Gamma. One of the main properties of the Gauss hypergeometric function is that its circle of convergence is the unit circle. Fortunately, there are some ways to define it outside the unit circle, the Euler integral representation being the most practical continuation formula

$$_2F_1(a, b, c; z) = \frac{\Gamma(c)}{\Gamma(b) \Gamma(c-b)} \int_0^1 t^{b-1} (1-t)^{c-b-1} (1-tz)^{-a} \, dt,$$

when $Re(c) > Re(b) > 0$ (see Abramowitz and Stegun, 15.3.1, page 558). Boucekkine and Ruiz-Tamarit show that the solutions of the system (11)-(14) can be written in terms of Gaussian hypergeometric functions in their Euler integral representation.

More precisely, let us define the hypergeometric function

$$_2F_1(t) = {}_2F_1 \left(a, b, c; \left(1 - \frac{\delta + n + \pi - \theta}{\epsilon} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{-\frac{1-\beta}{\beta}} \right) \exp \left\{ -\frac{(1-\beta)(\delta + n + \pi - \theta)}{\beta} t \right\} \right),$$

$$_2F_1(0) = {}_2F_1 \left(a, b, c; 1 - \frac{\delta + n + \pi - \theta}{\epsilon} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{-\frac{1-\beta}{\beta}} \right),$$

5

with

$$\epsilon = \beta A \left(\frac{(1 - \beta) A N_0}{\delta} \right)^{\frac{1-\beta}{\beta}} \ ,$$

$$a = -\frac{(\delta + n + \pi - \theta)(\beta - \sigma) - \beta(\rho + \pi - n\sigma - \pi\sigma)}{\sigma(\delta + n + \pi - \theta)(1 - \beta)}, \quad b = -\frac{\beta - \sigma}{\sigma(1 - \beta)}, \quad c = 1 + a.$$

Then the optimal trajectory of physical capital can be exactly characterized by the following proposition:

Proposition 1 *(i) The unique optimal positive path for the physical capital stock K, starting from $K_0 > 0$, is given by*

$$K = K_0 \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{\frac{1}{\beta}} \left(\frac{\epsilon}{\delta + n + \pi - \theta} \right)^{\frac{1}{1-\beta}} \frac{{}_2F_1(t)}{{}_2F_1(0)}$$

$$\cdot \exp \left\{ \frac{(\delta + n + \pi - \theta)(\beta - \sigma) - \beta(\rho + \pi - n\sigma)}{\beta\sigma} t \right\}$$

$$\cdot \left[-1 + \exp \left\{ \frac{(1 - \beta)(\delta + n + \pi - \theta)}{\beta} t \right\} + \frac{\delta + n + \pi - \theta}{\epsilon} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{-\frac{1-\beta}{\beta}} \right]^{\frac{1}{1-\beta}} ; \qquad (19)$$

(ii) this equilibrium path shows transitional dynamics, approaching asymptotically the unique positive balanced growth path

$$\bar{K} = \frac{K_0}{{}_2F_1(0)} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{\frac{1}{\beta}} \left(\frac{\epsilon}{\delta + n + \pi - \theta} \right)^{\frac{1}{1-\beta}} \exp \left\{ \frac{\delta + n - \theta - \rho + n\sigma}{\sigma} t \right\}, \qquad (20)$$

along which, given $\delta + n > \theta + \rho$, K grows permanently at a positive constant rate $\bar{g}_K = \frac{\delta + n - \theta - \rho + n\sigma}{\sigma}$.

Proof: See Boucekkine and Ruiz-Tamarit (2007), Proposition 4.

Similarly, one can define the auxiliary hypergeometric function for the solution path of human capital

$${}_2\widetilde{F}_1(t) = {}_2F_1 \left(\widetilde{a}, b, c; \left(1 - \frac{\delta + n + \pi - \theta}{\epsilon} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{-\frac{1-\beta}{\beta}} \right) \exp \left\{ -\frac{(1 - \beta)(\delta + n + \pi - \theta)}{\beta} t \right\} \right),$$

$${}_2\widetilde{F}_1(0) = {}_2F_1 \left(\widetilde{a}, b, c; 1 - \frac{\delta + n + \pi - \theta}{\epsilon} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)} \right)^{-\frac{1-\beta}{\beta}} \right),$$

with

$$\widetilde{a} = a - 1 = -\frac{(\delta + n + \pi - \theta)\beta(1 - \sigma) - \beta(\rho + \pi - n\sigma - \pi\sigma)}{\sigma(\delta + n + \pi - \theta)(1 - \beta)}.$$

Then the optimal human capital trajectory should fulfill the following proposition:

Proposition 2 *(i) The unique positive path for the human capital stock h, starting from $h_0 > 0$, is given by*

$$h = h_0 \frac{{}_2\widetilde{F}_1(t)}{{}_2\widetilde{F}_1(0)} \exp \left\{ \frac{\delta + n - \theta - \rho}{\sigma} t \right\}; \qquad (21)$$

(ii) Unless function $_2\widetilde{F}_1(t)$ is identically equal to 1, this equilibrium path shows transitional dynamics, approaching asymptotically to the unique positive balanced growth path

$$\overline{h}= \frac{h_0}{_2\widetilde{F}_1(0)} \exp\left\{ \frac{\delta + n - \theta - \rho}{\sigma}t\right\}, \tag{22}$$

along which, given $\delta + n > \theta + \rho$, h grows permanently at a positive constant rate $\overline{g}_h= \frac{\delta+n-\theta-\rho}{\sigma}$.

Proof: See Proposition 5 in Boucekkine and Ruiz-Tamarit (2007).

It should be noted that (19) to (22) characterize completely the solution paths for both stocks of capital in the short- and long-run provided that the shadow price values $\vartheta_1(0)$ and $\vartheta_2(0)$ be identified. Boucekkine and Ruiz-Tamarit (2007) set also this issue:

Proposition 3 *Any particular non-explosive solution to the dynamic system (11)-(14) has to satisfy the initial conditions K_0 and h_0, as well as the limit conditions (9) and (10).*

1. *The transversality conditions impose the constraints*

$$(\delta + n + \pi - \theta)(\beta - \sigma) - \beta(\rho + \pi - n\sigma - \pi\sigma) < -\sigma(1 - \beta)(\delta + n + \pi - \theta) < 0, \tag{23}$$

$$(\delta - \theta)(1 - \sigma) + n - \rho < 0, \tag{24}$$

$$\frac{K_0}{_2F_1(0)} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)}\right)^{\frac{1}{\beta}} = -\frac{\sigma\beta N_0 \vartheta_2(0)^{-\frac{1}{\sigma}} \left(\frac{\delta+n+\pi-\theta}{\epsilon}\right)^{\frac{\sigma-\beta}{\sigma(1-\beta)}}}{(\delta + n + \pi - \theta)(\beta - \sigma) - \beta(\rho + \pi - n\sigma - \pi\sigma)}, \tag{25}$$

$$\frac{_2F_1(0)}{_2\widetilde{F}_1(0)} = \frac{(1 - \beta)\epsilon\sigma}{-((\delta - \theta)(1 - \sigma) + n - \rho)\beta} \frac{K_0}{h_0} \left(\frac{\vartheta_1(0)}{\vartheta_2(0)}\right)^{\frac{1}{\beta}}.. \tag{26}$$

2. *Set $\Lambda = \frac{\delta+n+\pi-\theta}{\epsilon}$, $\eta = \frac{\vartheta_1(0)}{\vartheta_2(0)}$, and $z_0 = \left(1 - \Lambda\eta^{-\frac{1-\beta}{\beta}}\right)$. Then, if $\frac{K_0}{N_0 h_0} > \left(\frac{\overline{K}}{Nh}\right)$, we get $z_0 < 0$. If $\frac{K_0}{N_0 h_0} < \left(\frac{\overline{K}}{Nh}\right)$, we get $0 < z_0 < 1$. Finally, if $\frac{K_0}{N_0 h_0} = \left(\frac{\overline{K}}{Nh}\right)$, we have $z_0 = 0$.*

Proof: See Proposition 3, Lemma 2, Lemma 3 and Proposition 7 in Boucekkine and Ruiz-Tamarit (2007).

Remark 1: It should be noted here that condition (23) implies that parameter a of the hypergeometric functions defined above should satisfy $a > 1$. This is a very important property for the shape of optimal global dynamics as we shall see afterwards.

Remark 2: Note also that by construction, parameters a and b of the hypergeometric functions can be permuted; that is, $_2F_1(a, b, c; z) = {}_2F_1(b, a, c; z)$. Since $c = 1 + a$ and $a > 1$, it follows that conditions for the Euler integral representation hold for the two involved hypergeometric functions, namely $_2F_1(t)$ and $_2\widetilde{F}_1(t)$. Notice that the case where the Euler integral representation is allowed, the hypergeometric functions are necessarily positive.

Remark 3: Notice that Property 2 of the above Proposition 3 gives the position of the relative shadow price η depending upon the position of the initial physical capital to human capital ratio with respect to its long-run counterpart. Such a property is, of course, of crucial importance in the global study of the imbalance effects reported below.

4 Global dynamics and imbalance effects

We start with a brief discussion of the concept of imbalance effects. For the sake of simplicity, from now on we shall assume constant population ($n = 0$) normalized at $N_0 = 1$.

4.1 Imbalance effects: revisiting the concept

As mentioned in the introduction, the imbalance effects refer to the transition dynamics of an economy subject to an imbalance between initial and long-run values of the state variables. Such effects have been deeply studied in two-sector endogenous growth models, especially thanks to the contributions of Sala-i-Martin and his co-authors. Nonetheless, the analysis has been so far mostly computational, with the notable exception of Caballé and Santos (1993) and Ortigueira (1998). Using the 3-dimensional transformed Lucas-Uzawa model, and linearizing around the corresponding steady state, these authors have noticed that the transition dynamics depend strongly on the value of the capital share in the final good production function, β, and on the inverse of the intertemporal elasticity of substitution, σ. Ortigueira, in page 330, defines the *normal case* as follows:

Definition 1 *If the economy starts with a higher physical-human capital ratio than that of the stationary solution, then the (short-run) rate of human capital accumulation is higher than that of the long-run equilibrium. That is,*

$$\frac{K_0}{h_0} > \left(\frac{\bar{K}}{h}\right) \Rightarrow \frac{\dot{h}}{h} > \frac{\dot{\bar{h}}}{\bar{h}}$$

Then, he proves that the economy belongs to the normal case *if and only if* $\beta < \sigma$ (Corollary 1, page 332). The same result was obtained by Caballé and Santos (1993)[2]. The proof of such a property within the traditional approach is definitely easy since the growth rate of human capital is exclusively driven by $1 - u$ (i.e., the fraction of human capital channeled into the education sector), and the variable u is one of the three variables considered in the 3-dimensional auxiliary model. The transition dynamics of physical capital are then supplied numerically.

As argued in the introduction, we do believe that a more global appraisal of imbalance effects should take into account the two state variables, physical and human capital. The fact that the short-run rate of human capital accumulation is higher than that of the long-run equilibrium does not guarantee that the short-run rate of physical capital accumulation is lower than that of the long-run equilibrium. We shall therefore consider a more general definition of the *normal case* as follows:

Definition 2 *If the economy starts with a higher physical-human capital ratio than that of the stationary solution, then the short-run rate of human capital accumulation is higher than that of the long-run equilibrium, and the short-run rate of physical capital accumulation is lower than that of the long-run equilibrium. That is,*

$$\frac{K_0}{h_0} > \left(\frac{\bar{K}}{h}\right) \Rightarrow \frac{\dot{h}}{h} > \frac{\dot{\bar{h}}}{\bar{h}} \ ,$$

---

[2]It should be noted that Ortigueira's model also includes taxation of income from both capital stocks. Corollary 1, page 332, refers to the original Lucas-Uzawa model, without taxes.

and

$$\frac{K_0}{h_0} > \left(\frac{\bar{K}}{\bar{h}}\right) \Rightarrow \frac{\dot{K}}{K} < \frac{\dot{\bar{K}}}{\bar{K}}.$$

We are simply stating that in case of initial imbalance, the relatively scarce variable should grow at a higher rate than in the long-run, while the variable relatively in excess should have the opposite behaviour. The next section is first devoted to show that the parametric characterization of Caballé and Santos (1993) and Ortigueira (1998) can be extended to any initial conditions (global dynamics). Then, we will analyze the imbalance effects in the light of the stricter concept defined just above. We will highlight an important asymmetry between physical and human capital which is omitted in the related theoretical literature.

4.2 Human capital dynamics

We start, as in the traditional approach, with human capital dynamics.

Set $\Theta = \frac{(1-\beta)\epsilon\sigma}{-((\delta-\theta)(1-\sigma)-\rho)\beta}$, and recall that now $\epsilon = \beta A \left(\frac{(1-\beta)A}{\delta}\right)^{\frac{1-\beta}{\beta}}$ and $\Lambda = \frac{\delta+\pi-\theta}{\epsilon}$. Then, using equation (20) and (22) respectively, one can rewrite the balanced growth paths of physical and human capital stocks as

$$\bar{K} = \frac{K_0}{{}_2F_1(0)} \eta^{\frac{1}{\beta}} \frac{1}{\Lambda^{\frac{1}{1-\beta}}} \exp\left\{\frac{\delta-\theta-\rho}{\sigma}t\right\},$$

$$\bar{h} = \frac{h_0}{{}_2\widetilde{F}_1(0)} \exp\left\{\frac{\delta-\theta-\rho}{\sigma}t\right\}.$$

This allows to write the long-run ratio physical to human capital as

$$\left(\frac{\bar{K}}{\bar{h}}\right) = \frac{K_0}{h_0} \frac{{}_2\widetilde{F}_1(0)}{{}_2F_1(0)} \frac{1}{\Lambda^{\frac{1}{1-\beta}}} \eta^{\frac{1}{\beta}}. \tag{27}$$

Therefore, if the economy starts from above, that is $\frac{K_0}{h_0} > \left(\frac{\bar{K}}{\bar{h}}\right)$, we have

$$1 > \frac{{}_2\widetilde{F}_1(0)}{{}_2F_1(0)} \frac{1}{\Lambda^{\frac{1}{1-\beta}}} \eta^{\frac{1}{\beta}} \tag{28}$$

or, using the transversality condition (26) from Proposition 3,

$$\frac{K_0}{h_0} > \frac{1}{\Theta} \frac{1}{\Lambda^{\frac{1}{1-\beta}}}. \tag{29}$$

We shall now study the growth rate of human capital using the closed-form solution of this variable given in Proposition 2 by equation (21), that is

$$h = h_0 \frac{{}_2\widetilde{F}_1(t)}{{}_2\widetilde{F}_1(0)} \exp\left\{\frac{\delta-\theta-\rho}{\sigma}t\right\}.$$

Comparing with (22), one gets immediately h as a function of $\bar{h}$ and ${}_2\widetilde{F}_1(t)$, which is very useful for the inspection of imbalance effects,

$$h = {}_2\widetilde{F}_1(t)\,\bar{h}\,. \tag{30}$$

Indeed, it follows immediately that

$$\frac{\dot{h}}{h} = \frac{{}_2\dot{\widetilde{F}}_1(t)}{{}_2\widetilde{F}_1(t)} + \frac{\dot{\bar{h}}}{\bar{h}}, \tag{31}$$

and finally we may conclude

$$\frac{\dot{h}}{h} > \frac{\dot{\bar{h}}}{\bar{h}} \iff \frac{{}_2\dot{\widetilde{F}}_1(t)}{{}_2\widetilde{F}_1(t)} > 0.$$

It is then almost trivial to obtain a global counterpart of Ortigueira's result on the parametric characterization of the normal case:

Proposition 4 *If the economy is characterized by $\sigma > \beta$, and only in this case, we have*

$$\frac{K_0}{h_0} > \left(\frac{\bar{K}}{\bar{h}}\right) \Rightarrow \frac{\dot{h}}{h} > \frac{\dot{\bar{h}}}{\bar{h}}$$

Proof: The proof is somewhat immediate after the computation of the growth rate of the hypergeometric function ${}_2\widetilde{F}_1(t)$. The algebra needed for such a computation is trivial for special functions users and it is reported in the Appendix. We get

$$\frac{{}_2\dot{\widetilde{F}}_1(t)}{{}_2\widetilde{F}_1(t)} > 0 \iff \frac{b(a-1)}{a+1}\dot{z}(t)\frac{{}_2F_1(b+1,a,a+2;z(t))}{{}_2F_1(b,a-1,a+1;z(t))} > 0,$$

with $z(t) = z_0 \exp\left\{-\frac{(1-\beta)(\delta+\pi-\theta)}{\beta}t\right\}$. Notice that since we start from above, Property 2 of Proposition 3 implies that $z_0 < 0$. Because

$$\dot{z}(t) = -\frac{(1-\beta)(\delta+\pi-\theta)}{\beta}z_0 \exp\left\{-\frac{(1-\beta)(\delta+\pi-\theta)}{\beta}t\right\},$$

and by transversality condition (23) we get $\delta + \pi > \theta$, it follows that $\dot{z}(t)$ is strictly positive. Now, it is sufficient to look at the expression of $\frac{{}_2\dot{\widetilde{F}}_1(t)}{{}_2\widetilde{F}_1(t)}$ just above to get the result. Since $a > 1$, and the involved hypergeometric functions ${}_2F_1(b+1,a,a+2;z(t))$ and ${}_2F_1(b,a-1,a+1;z(t))$ are strictly positive[3], the sign of $\frac{{}_2\dot{\widetilde{F}}_1(t)}{{}_2\widetilde{F}_1(t)}$ is the sign of $b = -\frac{\beta-\sigma}{\sigma(1-\beta)}$. $\square$

4.3   The dynamics of physical capital

We now move to the dynamics of physical capital, and provide a similar global analysis as for human capital in accordance with our interpretation of imbalance effects. Not surprisingly, the task proves more difficult than for human capital. However the algebra needed is by no way intractable.

---

[3]This is because they admit the Euler integral representation, see Remark 2 above.

Let us first recall the closed-form solution for physical capital given in Proposition 1 by equation (19),

$$K = K_0 \eta^{1/\beta} \left(\frac{1}{\Lambda} \right)^{\frac{1}{1-\beta}} \frac{{}_2F_1(t)}{{}_2F_1(0)} \exp\left\{ \frac{(\delta + \pi - \theta)(\beta - \sigma) - \beta(\rho + \pi)}{\beta\sigma} t \right\}$$

$$.. \left[-z_0 + \exp\left\{ \frac{(1-\beta)(\delta + \pi - \theta)}{\beta} t \right\} \right]^{\frac{1}{1-\beta}}.$$

Comparing with the balanced growth path given in Proposition 1 by equation (20), we can rewrite K into a more interesting and manageable form given our purposes,

$$K(t) = \bar{K}(t) \, {}_2F_1(t) \, G(t),$$

where

$$G(t) = \exp\left\{ \frac{(-(\delta + \pi - \theta))}{\beta} t \right\} \left[-z_0 + \exp\left\{ \frac{(1-\beta)(\delta + \pi - \theta)}{\beta} t \right\} \right]^{\frac{1}{1-\beta}}.$$

Then, the growth rate of physical capital is given by

$$\frac{\dot{K}}{K} = \frac{\dot{\bar{K}}}{\bar{K}} + \frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)} + \frac{\dot{G}(t)}{G(t)}. \tag{32}$$

Accordingly, for physical capital to behave in accordance with the normal case defined in Section 4.1, we need to assess the inequality

$$\frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)} + \frac{\dot{G}(t)}{G(t)} < 0,$$

when the economy starts with a physical to human capital ratio above its long-run counterpart. We shall first prove that if we are in the *normal* parametric case identified by Caballé and Santos, then such an inequality is indeed fulfilled.

Proposition 5 *When the economy starts with a higher physical-human capital ratio than that of the stationary solution and the condition $\beta < \sigma$ is checked, the short-run rate of physical capital accumulation is lower than that of the long-run equilibrium.*

Proof: Using the Euler integral representation of the hypergeometric function ${}_2F_1(t)$ one finds, after some trivial algebra,

$$\frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)} = -bz_0 \frac{(1-\beta)(\delta + \pi - \theta)}{\beta} \exp\left\{ -\frac{(1-\beta)(\delta + \pi - \theta)}{\beta} t \right\} \frac{a}{a+1}$$

$$\frac{{}_2F_1(b+1, a+1, a+2; z(t))}{{}_2F_1(b, a, a+1; z(t))},$$

where $z(t) = z_0 \exp\{-\frac{(1-\beta)(\delta + \pi - \theta)}{\beta} t\}$ as before. Note that $\frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)}$ is a positive function that tends to $-bz_0 \frac{(1-\beta)(\delta + \pi - \theta)}{\beta} \frac{a}{a+1} \frac{{}_2F_1(b+1, a+1, a+2; z_0)}{{}_2F_1(b, a, a+1; z_0)}$ when $t \to 0$, and tends to 0 when $t \to \infty$. On the other hand,

$$\frac{\dot{G}(t)}{G(t)} = \frac{(\delta + \pi - \theta)}{\beta} \frac{z_0}{-z_0 + \exp\left\{ \frac{(1-\beta)(\delta + \pi - \theta)}{\beta} t \right\}},$$

which is a negative function that tends to $\frac{\delta + \pi - \theta}{\beta} \frac{z_0}{1 - z_0}$ when $t \to 0$, and tends to 0 when $t \to \infty$. So unfortunately, the sign of $\frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)} + \frac{\dot{G}(t)}{G(t)}$ is undetermined at this stage, and we have to dig deeper. Using the two previous expressions we find that[4]

$$\frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)} + \frac{\dot{G}(t)}{G(t)} = -\frac{(\delta + \pi - \theta)z}{\beta}\left[\frac{ba(1 - \beta)}{a + 1}\frac{{}_2F_1(b + 1, a + 1, a + 2; z)}{{}_2F_1(b, a, a + 1; z)} - \frac{1}{1 - z}\right]. \quad (33)$$

Applying formula (15.2.1) from Abramowitz and Stegun (1972), we can rewrite the previous expression in a more advantageous way

$$\frac{{}_2\dot{F}_1(t)}{{}_2F_1(t)} + \frac{\dot{G}(t)}{G(t)} = -\frac{(\delta + \pi - \theta)(1 - \beta)z}{\beta}\left[\frac{\frac{d[{}_2F_1(b, a, a+1; z)]}{dz}}{{}_2F_1(b, a, a + 1; z)} - \frac{1}{1 - \beta}\frac{1}{1 - z}\right]. \quad (34)$$

Given that by transversality condition (23) we get $\delta + \pi > \theta$, and $z < 0$ because by Proposition 3 $z_0 < 0$ when the initial physical to human capital ratio is above its long-run value, it follows that the short-run rate of physical capital accumulation is lower than that of the long-run equilibrium *if and only if*

$$\frac{\frac{d[{}_2F_1(b, a, a+1; z)]}{dz}}{{}_2F_1(b, a, a + 1; z)} - \frac{1}{1 - \beta}\frac{1}{1 - z} < 0, \quad \forall z < 0. \quad (35)$$

Integrating the previous inequality between z (< 0) and 0, we obtain that the latter inequality is indeed equivalent to

$$ {}_2F_1(b, a, a + 1; z) - (1 - z)^{-\frac{1}{1 - \beta}} > 0, \quad \forall z < 0. \quad (36)$$

We denote by $H(z)$ the function defined as the expression on the left hand side of the previous inequality. Then, the short-run rate of physical capital accumulation is lower than that of the long-run equilibrium *if and only if* $H(z)$ is positive $\forall z < 0$.

Suppose $\sigma > \beta$ or $b > 0$. We shall prove that in such a parametric case: (*i*) $H(0) = 0$, $H'(0) < 0$, and the limit of $H(z)$ when z tends to $-\infty$ is zero, and (*ii*) $H'(z)$ has a unique root. These conditions are sufficient for $H(z)$ positive $\forall z < 0$.

Note that $H(0) = {}_2F_1(b, a, a + 1; 0) - 1 = 0$. By continuity, $H(z) \to 0$ when $z \to 0$. This result implies, in our dynamical model, that $\frac{\dot{K}}{K}$ tends to $\frac{\dot{\bar{K}}}{\bar{K}}$ when t tends to ∞. Moreover,

$$H'(z) = \frac{ab}{1 + a}{}_2F_1(b + 1, a + 1, a + 2; z) - \frac{1}{1 - \beta}(1 - z)^{-\frac{2 - \beta}{1 - \beta}}, \quad (37)$$

which implies that

$$H'(0) = \frac{ab}{1 + a} - \frac{1}{1 - \beta} = \frac{1}{1 - \beta}\left(\frac{a}{a + 1}\frac{\sigma - \beta}{\sigma} - 1\right) < 0.$$

In order to prove that $H(z)$ goes to zero when z goes to $-\infty$, we use the Euler integral representation of the hypergeometric function ${}_2F_1(b, a, a + 1; z)$ to find an upper bound

---

[4]For the sake of simplicity, from now on we have removed the temporal index corresponding to the variable z.

going to zero when z goes to $-\infty$. This will be enough to conclude since $_2F_1\,(.)$ is positive $\forall z < 0$ and the limit of $(1-z)^{-\frac{1}{1-\beta}}$ is zero when z tends to $-\infty$. Indeed,

$$_2F_1(b,a,a+1;z) = \frac{\Gamma(a+1)}{\Gamma(a)\Gamma(1)}\int_0^1 v^{a-1}(1-vz)^{-b}dv \leq a\int_0^1 (1-vz)^{-b}dv$$

$$= \frac{a}{(1-b)z} - \frac{a\,(1-z)^{1-b}}{(1-b)\,z}.$$

The limit of the first term on the right hand side when z tends to $-\infty$ is zero, but it is also zero the limit of the second term when $b > 0$. The latter being obvious if $b > 1$, and immediate if $1 > b > 0$ after application of the l'Hôpital's rule. This allows already to conclude that $H(z)$ goes to zero when z goes to $-\infty$ under $b > 0$.

Now, recall (37) denoting $h_1(z) = \frac{ab}{1+a}\,_2F_1(b+1,a+1,a+2;z)$ and $h_2(z) = \frac{1}{1-\beta}(1-z)^{-\frac{2-\beta}{1-\beta}}$ so that $H'(z) = h_1(z) - h_2(z)$. It can be easily shown that both functions $h_1(.)$ and $h_2(.)$ are both strictly increasing and strictly convex for $z < 0$. Moreover, one can readily see that both functions cannot intersect in more than 2 points if any intersection. We shall show that the two functions do always intersect in a single point. Because of $H'(0) < 0$, we know that $h_1(0) < h_2(0)$. We now show that this inequality should be reverted for z big enough (in absolute value). Indeed, one can straightforwardly find a lower bound for $h_1(z)$ because

$$_2F_1(b+1,a+1,a+2;z) =$$

$$(1+a)\int_0^1 v^a(1-vz)^{-b-1}dv \geq (1+a)(1-z)^{-b-1}\int_0^1 v^a dv = (1-z)^{-b-1}.$$

Using this result we can see that

$$\frac{h_1(z)}{h_2(z)} \geq \frac{ab}{1+a}(1-\beta)(1-z)^{-b-1+\frac{2-\beta}{1-\beta}}.$$

Then, omitting the constant terms, it follows that the ratio $h_1(z)$ to $h_2(z)$ behaves like the function $(1-z)^\phi$, with $\phi = -b-1+\frac{2-\beta}{1-\beta} = \frac{1}{1-\beta} - b > 0$ as shown above. Hence, $h_1(z)$ is necessarily above function $h_2(z)$ for z large enough (in absolute value). This implies not only that $H'(z) = 0$ has a root but also that it can not have two. $\square$

It should be noted that the statement of Proposition 5 is a sufficient condition for *normal* dynamics in K: $b > 0$ is such a condition. Instead, for human capital Proposition 4 shows that *normal* dynamics are obtained **if and only if** $b > 0$. Actually, one can go a step further and show that whatever the value of b, we get always *normal* dynamics for K. This features a kind of asymmetry between the two capital stocks, which is hidden in the theoretical literature taking the traditional approach[5]. We prove this property next.

Proposition 6 *When the economy starts with a higher physical-human capital ratio than that of the stationary solution, the short-run rate of physical capital accumulation is lower than that of the long-run equilibrium whatever the sign of $\sigma - \beta$.*

Proof: The proof is trivial using the previous proposition and equation (37). If $b \leq 0$, then $H'(z) < 0$ for all $z \leq 0$. Since $H(0) = 0$, this means that $H(z)$ is always positive for z negative.$\square$

---

[5]It is fair to recognize that this feature is neatly pointed out in the computational literature à la Sala-i-Martin.

5   Conclusion

In this paper, we have shown how the closed-form solutions of the Lucas-Uzawa model, found out by Boucekkine and Ruiz-Tamarit (2007), can be advantageously used to dig deeper in some traditional economic topics in multi-sector models. It have been shown that not only these new solutions allow for an inspection into the imbalance effects for any initial conditions and for all variables in level (which is a highly desirable perspective for this kind of inspections), but it also allows to capture some important features missed by the related literature taking the traditional local approach. Non-monotonicity or asymmetry (between state variables) are some of the new insights brought out by the new approach. It should be noted that beside the important initial effort which was needed to compute the closed-form solutions, the properties demonstrated in this paper only require the very simple algebra of special functions.

References

[1] M. Abramowitz and I. A. Stegun, *Handbook of Mathematical Functions*. Dover Publications (1972).

[2] R. Barro and X. Sala-i-Martin, *Economic Growth*. McGraw-Hill (1995)

[3] J. Benhabib and R. Perli, Uniqueness and Indeterminacy: On the Dynamics of Endogenous Growth, *Journal of Economic Theory* **63** (1994), 113–142.

[4] R. Boucekkine and J. R. Ruiz-Tamarit, Special Functions of the Study of Economic Dynamics: The Case of the Lucas-Uzawa Model, *Journal of Mathematical Economics*, forthcoming, (2007).

[5] J. Caballé and M. S. Santos, On Endogenous Growth with Physical and Human Capital, *Journal of Political Economy* **101** (1993), 1042–1067.

[6] R. E. Lucas, Jr., On the Mechanics of Economic Development, *Journal of Monetary Economics* **22** (1988), 3-42.

[7] C. B. Mulligan and X. Sala-i-Martín, Transitional Dynamics in Two Sector Models of Endogenous Growth, *Quarterly Journal of Economics* **108** (1993), 739–773.

[8] S. Ortigueira, Fiscal Policy in an Endogenous Growth Model with Human Capital Accumulation, *Journal of Monetary Economics* **42** (1998), 323–355.

[9] D. Xie, Divergence in Economic Performance: Transitional Dynamics with Multiple Equilibria, *Journal of Economic Theory* **63** (1994), 97–112.

Appendix

Using the symmetry property in the arguments a and b, and taking into account that $\widetilde{a} = a - 1$ and $c = a + 1$, we can rewrite $_2\widetilde{F}_1(t)$ as

$$_2\widetilde{F}_1(t) = {}_2F_1(\widetilde{a}, b, c; z(t)) = {}_2F_1(a - 1, b, a + 1; z(t)) = {}_2F_1(b, a - 1, a + 1; z(t)).$$

Since the previous hypergeometric function checks conditions under which the Euler integral representation holds ($a + 1 > a - 1 > 0$), we can rewrite it as

$$_2F_1(\widetilde{a}, b, c; z(t)) = {}_2F_1(b, a-1, a+1; z(t)) = \frac{\Gamma(a+1)}{\Gamma(a-1)\Gamma(2)} \int_0^1 v^{a-2}(1-v)(1-vz(t))^{-b}dv =$$

$$a(a-1) \int_0^1 v^{a-2}(1-v)(1-vz(t))^{-b}dv.$$

The derivative of the previous expression with respect to t is

$$\dot{\widetilde{{}_2F_1}}(t) = a(a-1)b\dot{z}(t) \int_0^1 v^{a-1}(1-v)(1-vz(t))^{-b-1}dv.$$

Since

$$\int_0^1 v^{a-1}(1-v)(1-vz(t))^{-b-1}dv = \frac{\Gamma(a)\Gamma(2)}{\Gamma(a+2)}{}_2F_1(b+1, a, a+2; z(t)) =$$

$$= \frac{1}{a(a+1)}{}_2F_1(b+1, a, a+2; z(t)),$$

then

$$\dot{\widetilde{{}_2F_1}}(t) = b\,\dot{z}(t)\,\frac{a-1}{a+1}\,{}_2F_1(b+1, a, a+2; z(t)).$$

Finally, we get

$$\frac{\dot{\widetilde{{}_2F_1}}(t)}{\widetilde{{}_2F_1}(t)} = b\,\dot{z}(t)\,\frac{a-1}{a+1}\,\frac{{}_2F_1(b+1, a, a+2; z(t))}{{}_2F_1(b, a-1, a+1; z(t))}.$$